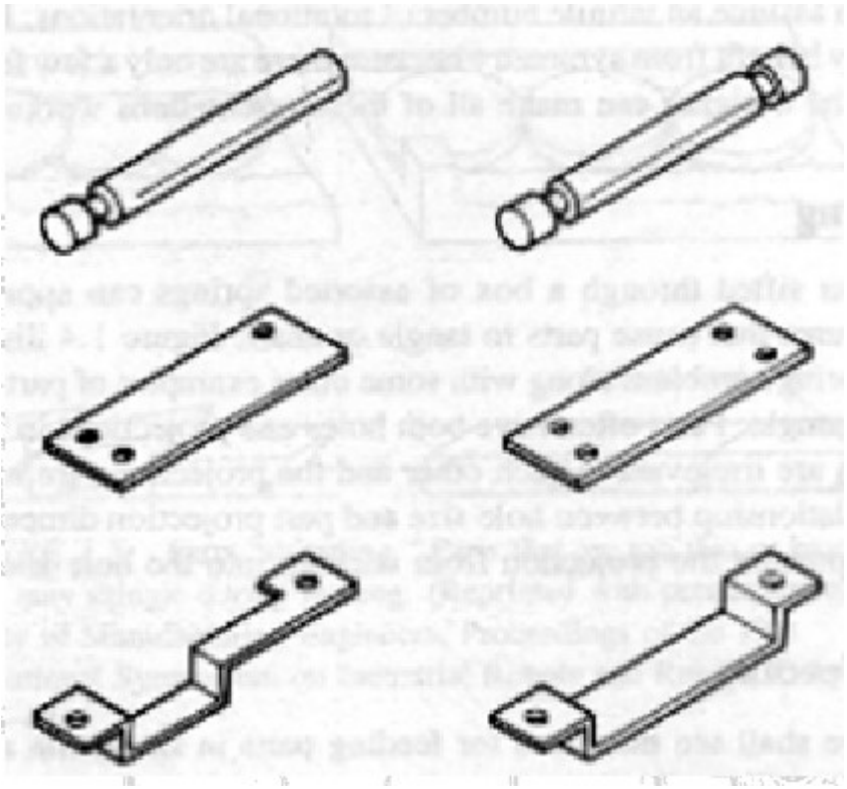
Care & Feeding of Machines

- Feeding parts
  - orientation
  - singulation
- Material obtained from:
  - Boothroyd, Automatic Assembly
  - Ken Goldberg, UCB Industrial Engr Oper. Rsrch (http://www.ieor.berkeley.edu/~goldberg/index.html)
  - Robert-Paul Berretty, PhD thesis, Utrecht (http://www.library.uu.nl/digiarchief/dip/diss/1940512/full.pdf)

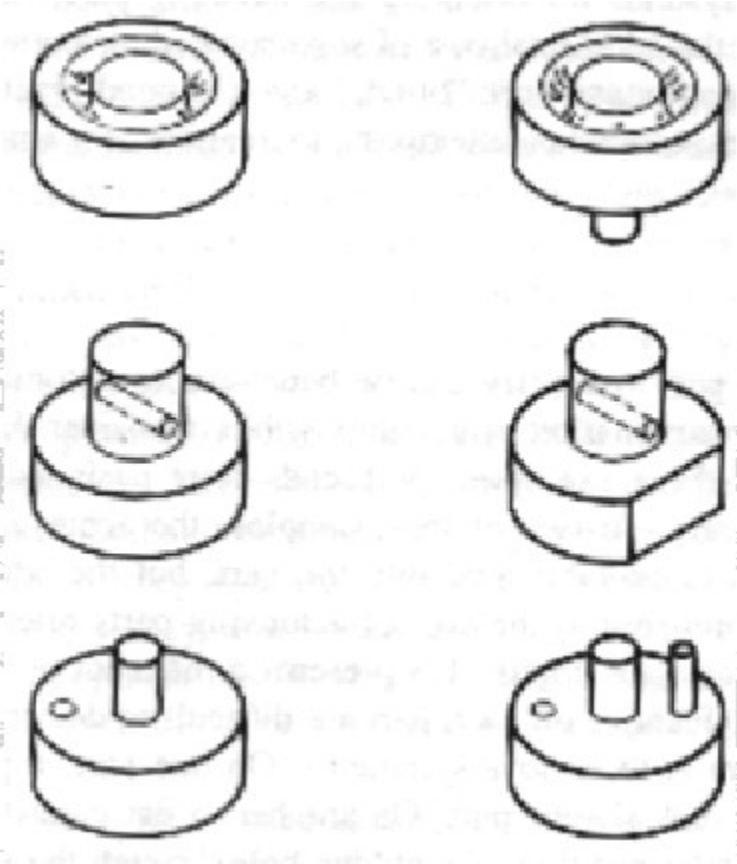
Designing Parts for Feeding

- Symmetry
- Asymmetry
- Tangling
- Shingling
- Wedging

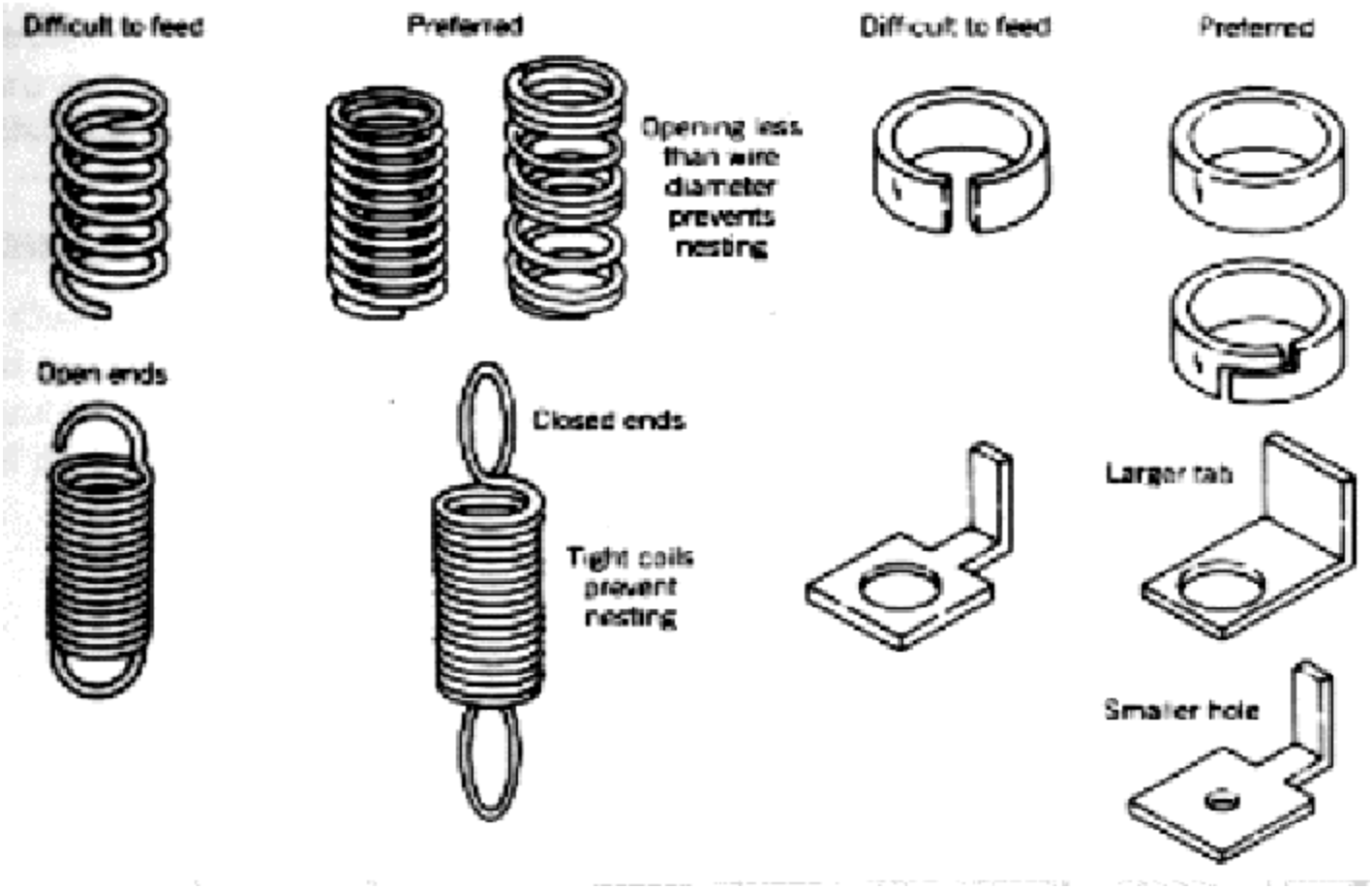
Symmetry



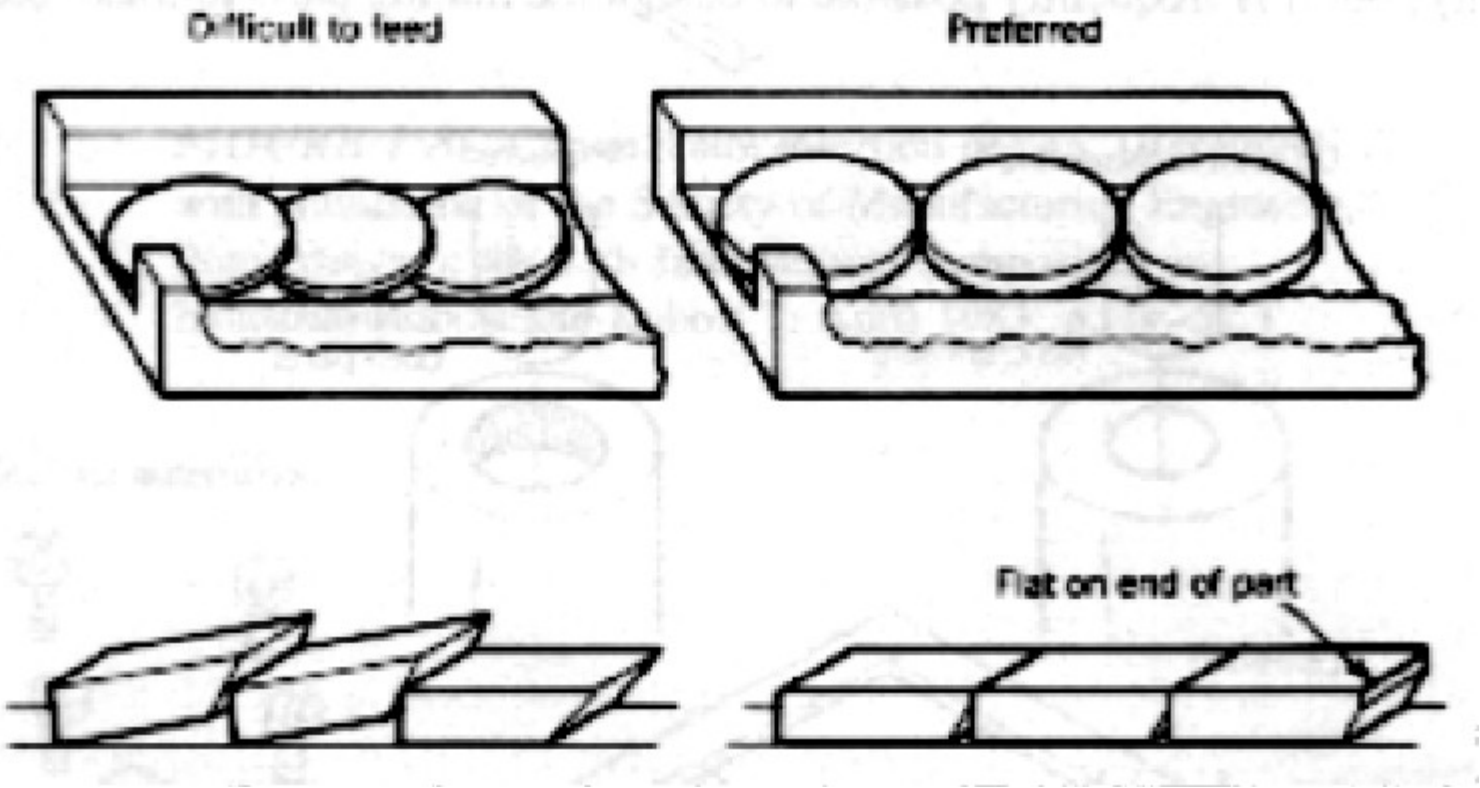
Asymmetry



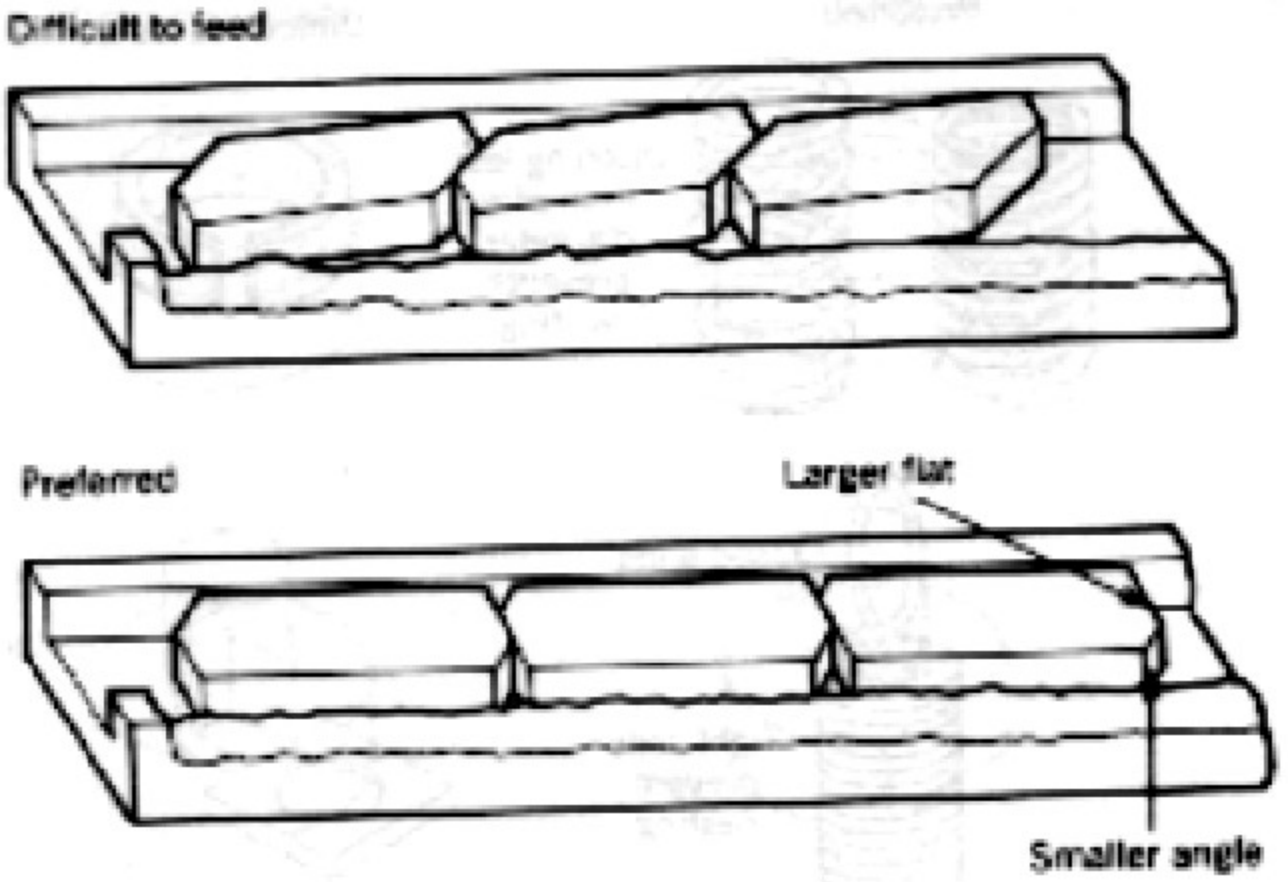
Tangling


Difficult to feed
Preferred
Opening less than wire diameter prevents nesting
Open ends
Closed ends
Tight coils prevent nesting
Difficult to feed
Preferred
Larger tab
Smaller hole

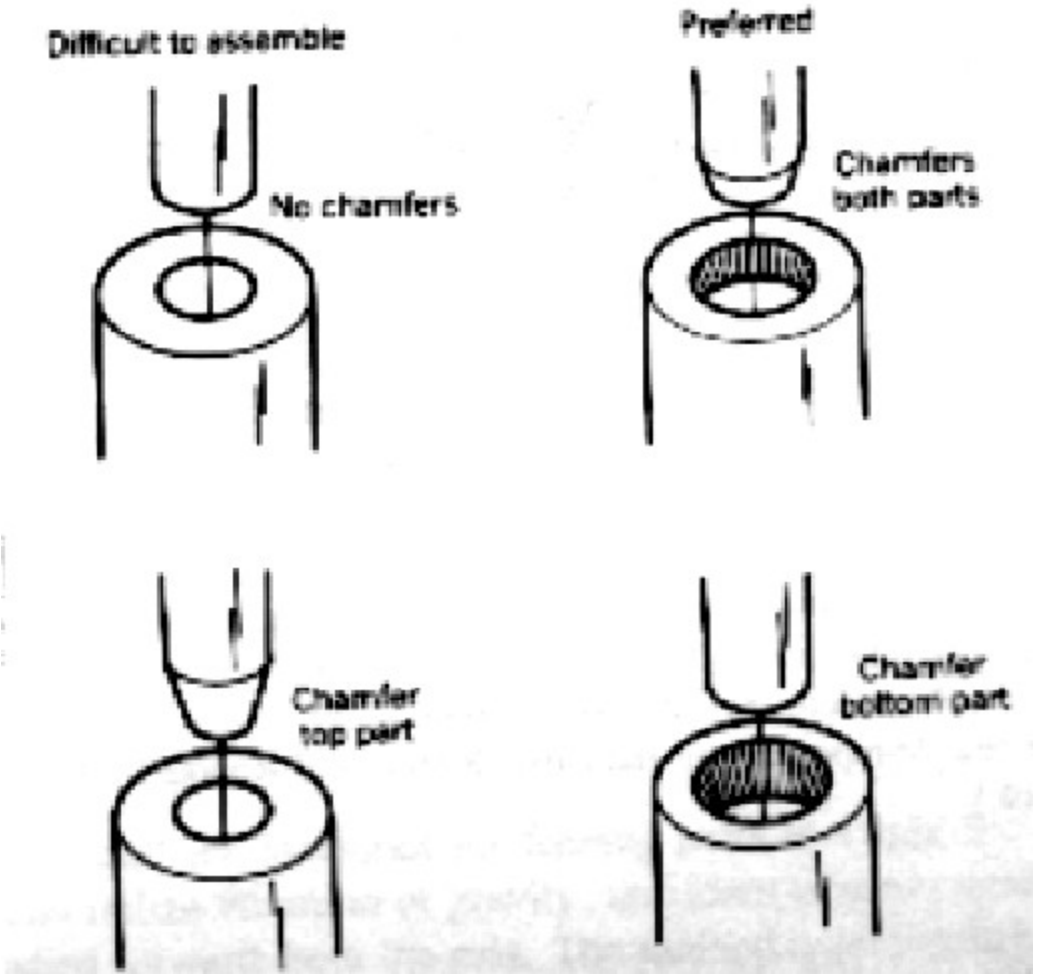
Shingling



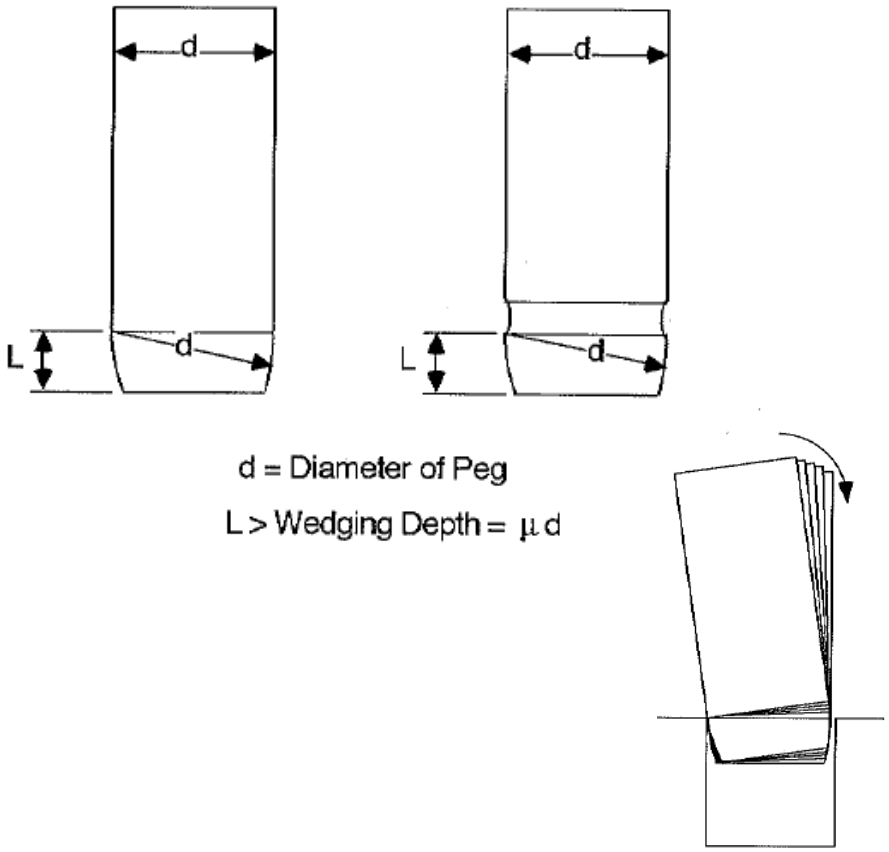
Wedging

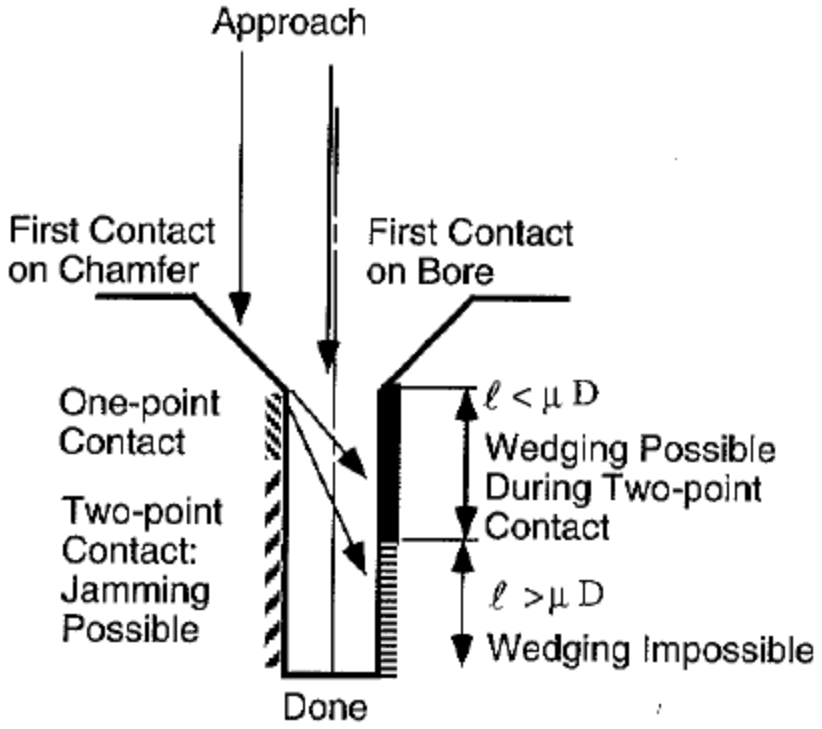


Designing for Insertion

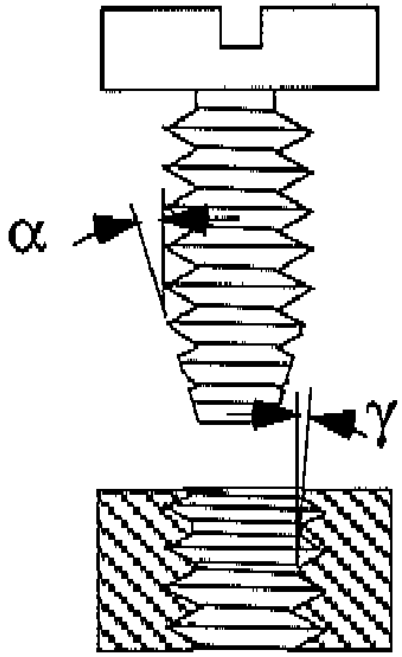


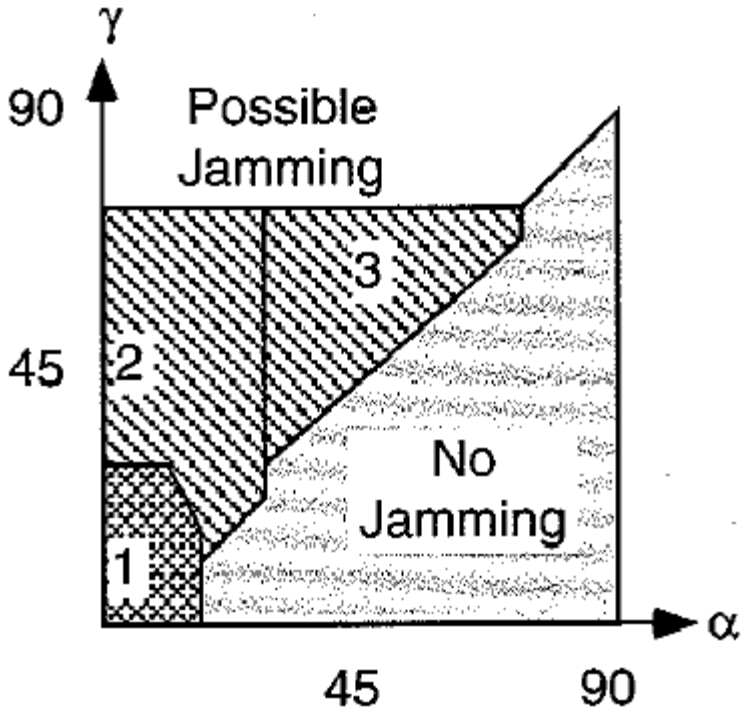
Inserting Pegs in Round Holes



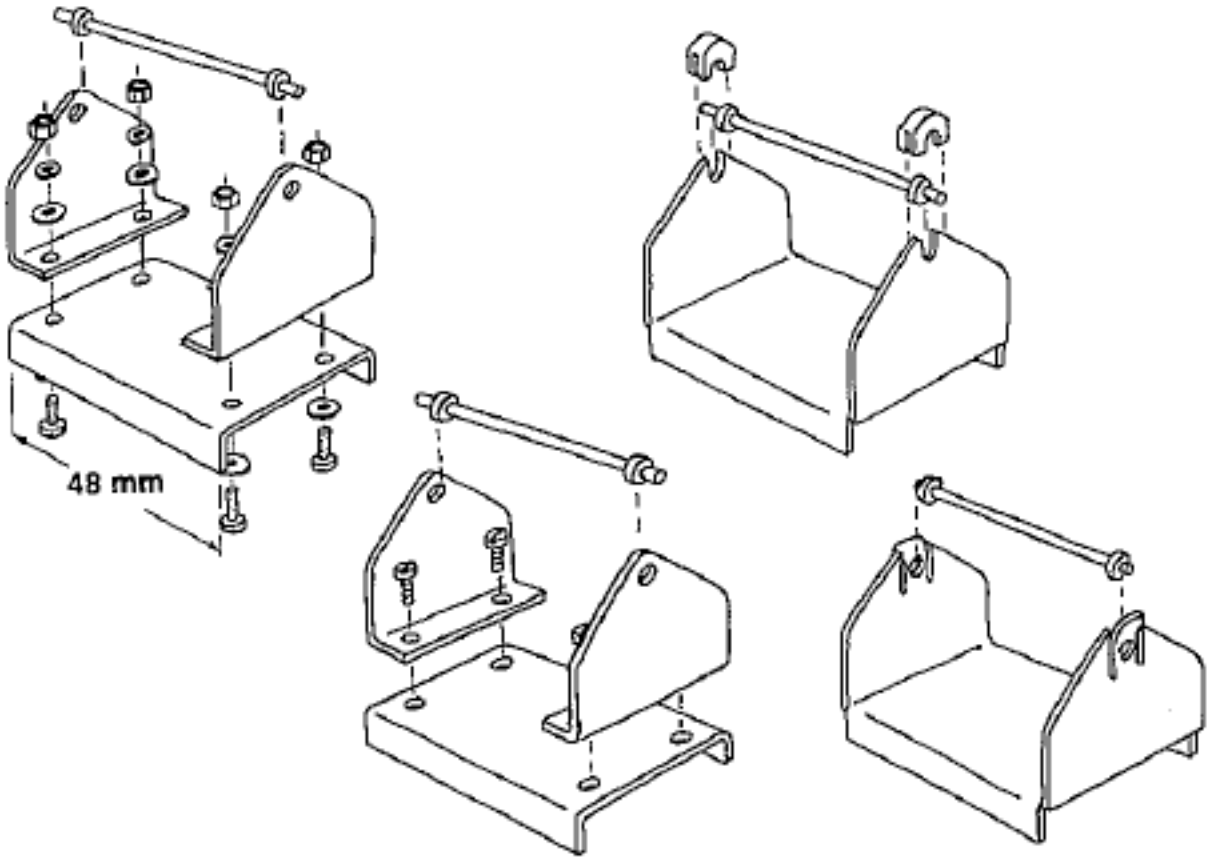


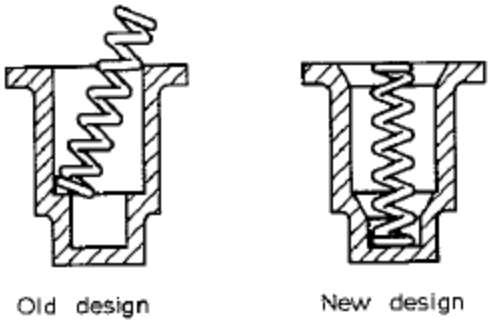
Screw Thread Mating





Simplifying the Design





Fastener Feeding Requirements

- Orientation
  - vibrating bowl
  - non-vibrating feeders
    - (see Boothroyd - Assembly Automation)
- Singulation
  - escapement mechanisms
  - pick and place
- Vision and Robots
- Pre-collated components

Singulation

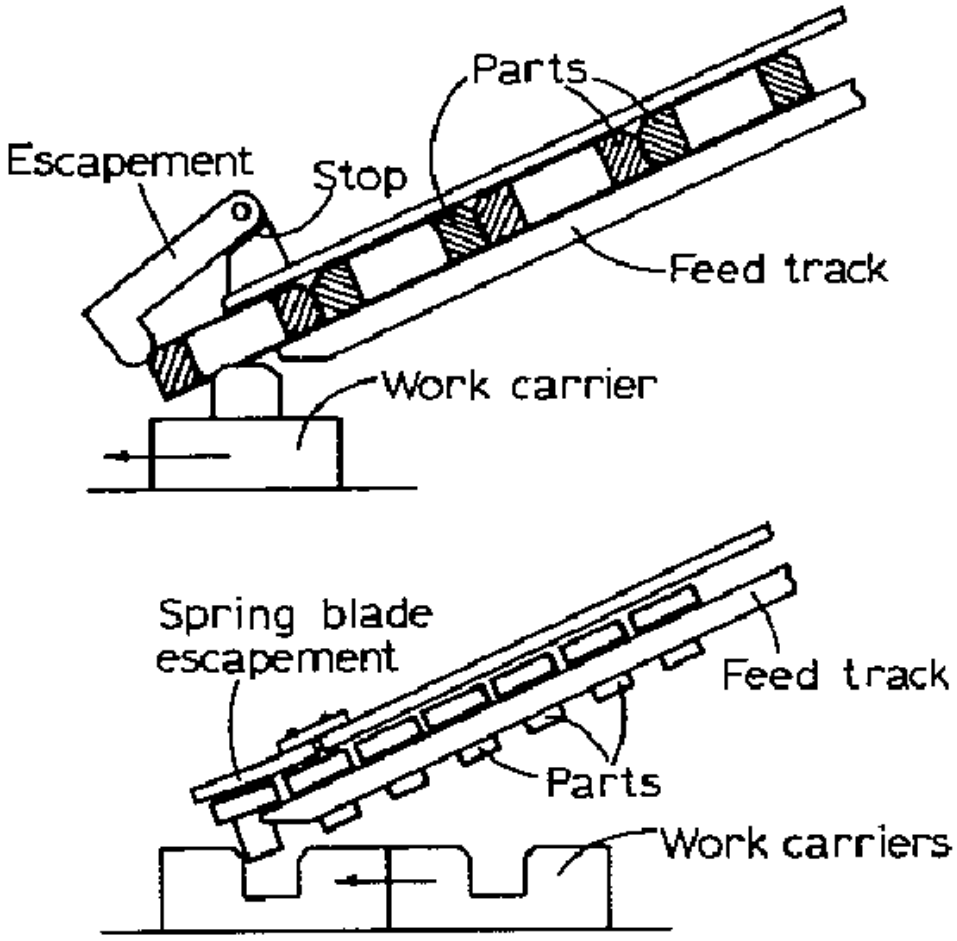


Fig. 5.24 Escapements actuated by the work carrier.

Singulation

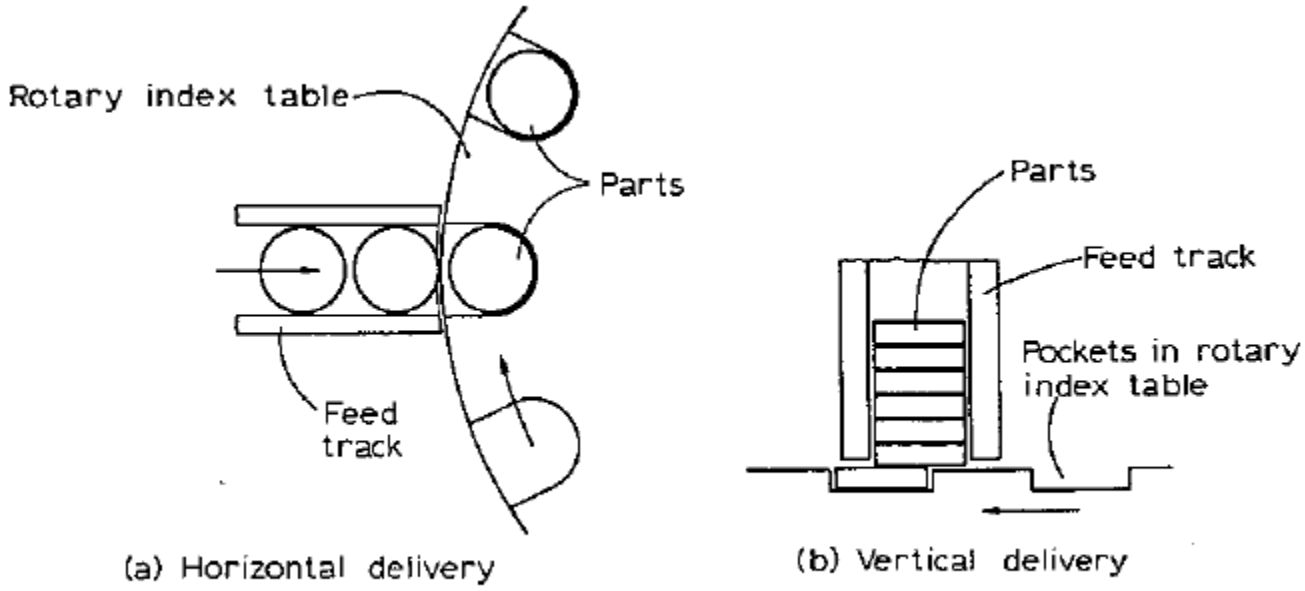


Fig. 5.25 Feeding of parts onto rotary index table.

Singulation

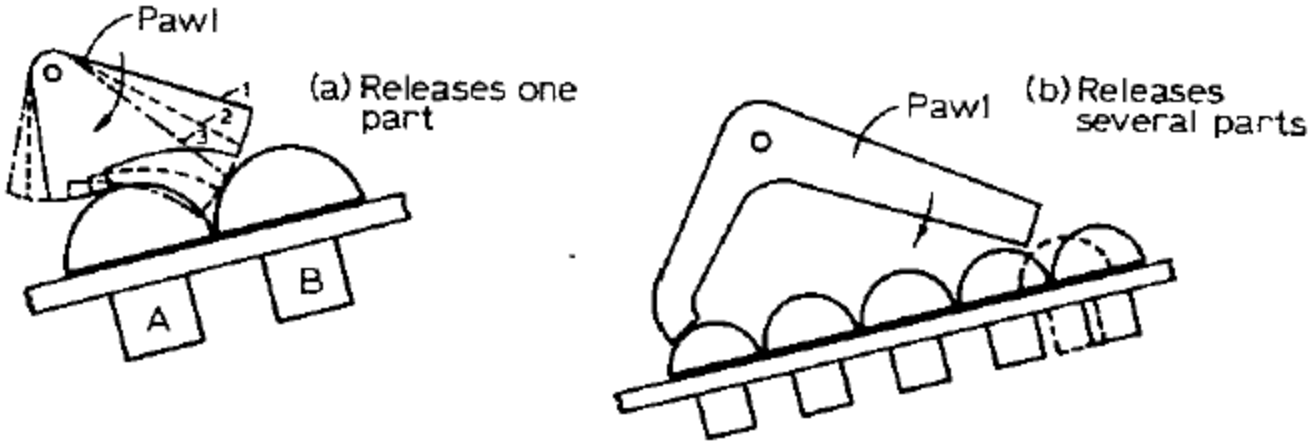


Fig. 5.26 Rachet escapements operated by rotary motion.

Singulation

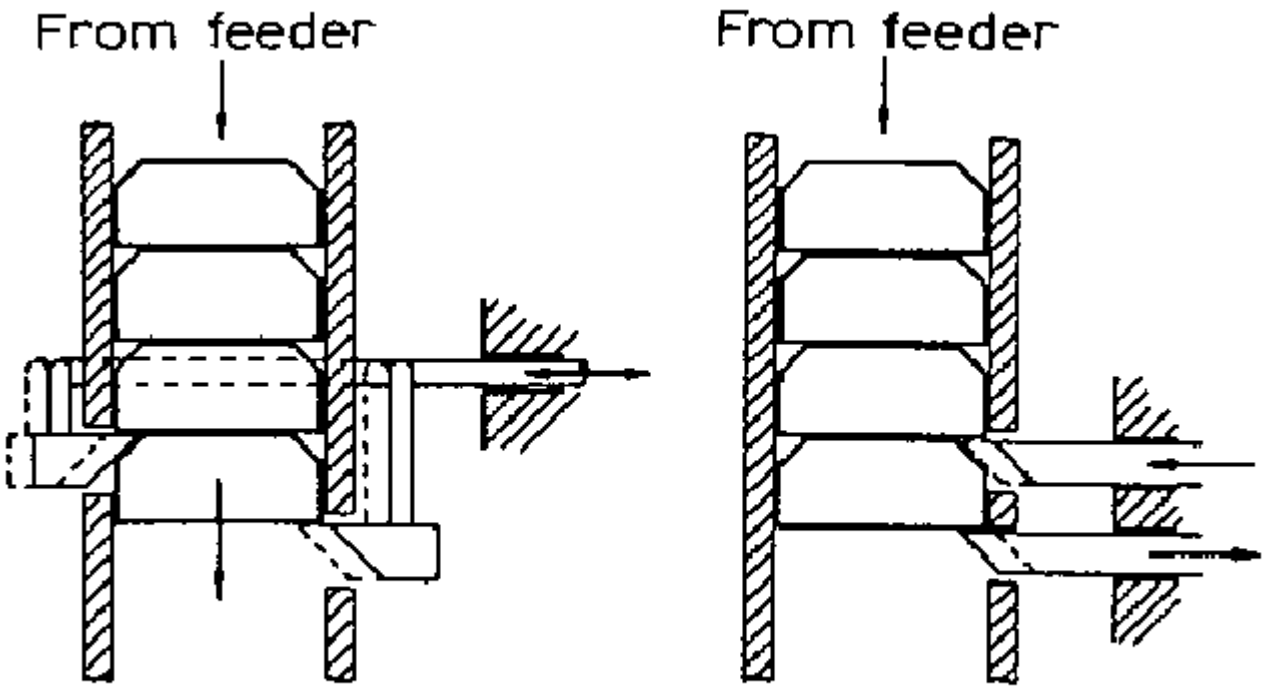
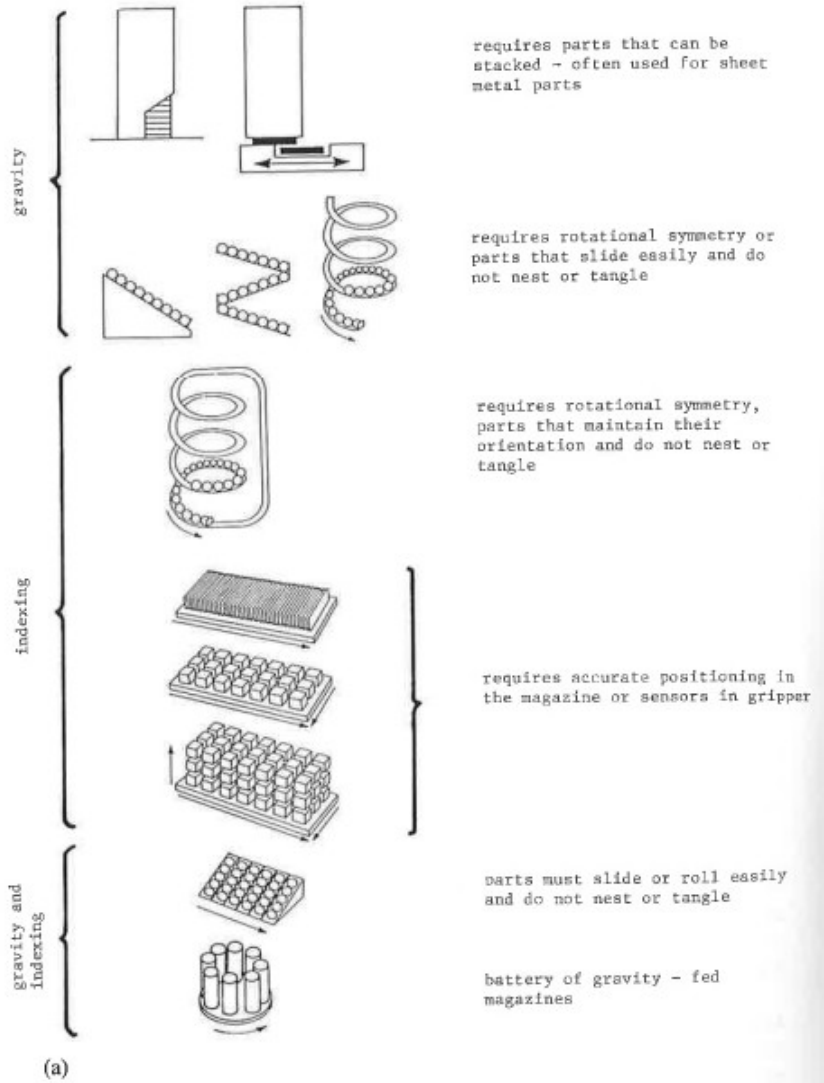
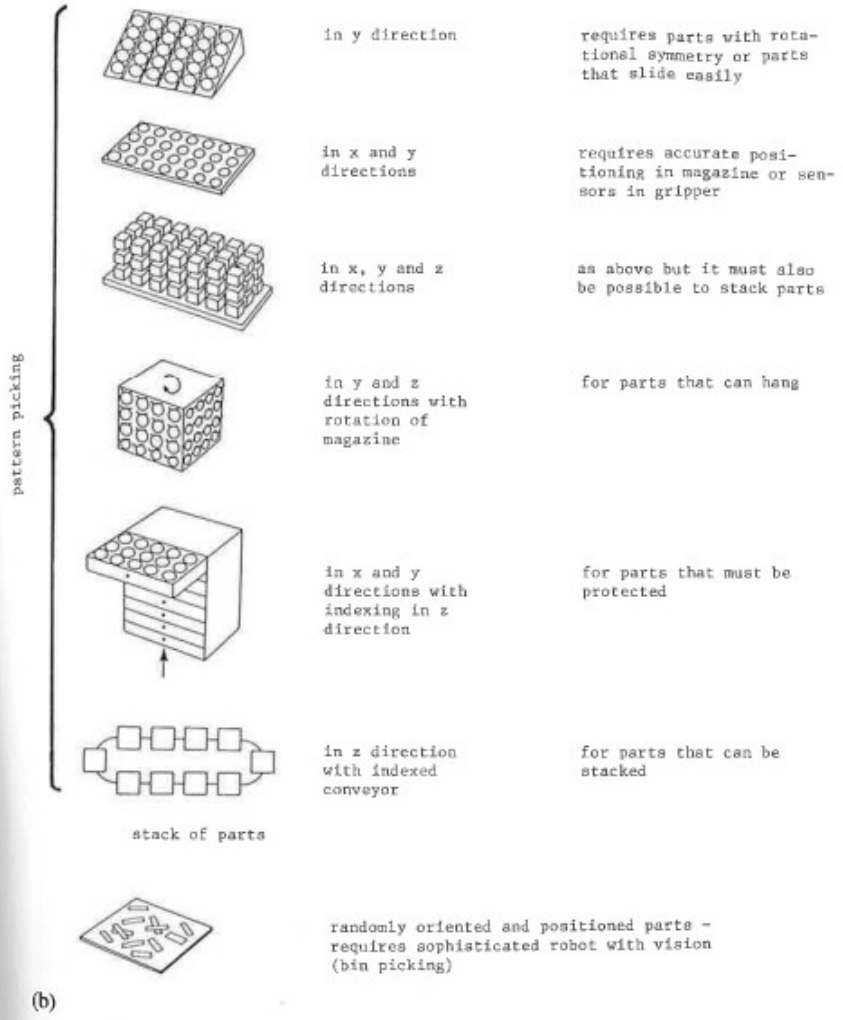


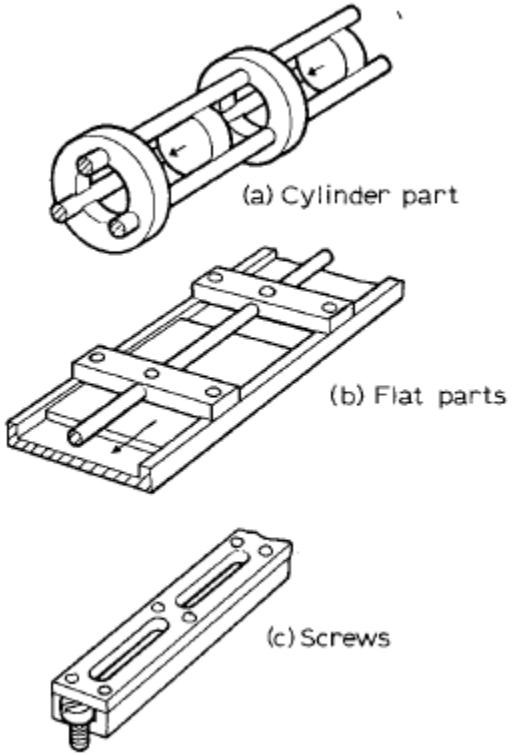
Fig. 5.27 Ratchet escapements operated by linear motion.

Variety of Feeding Methods





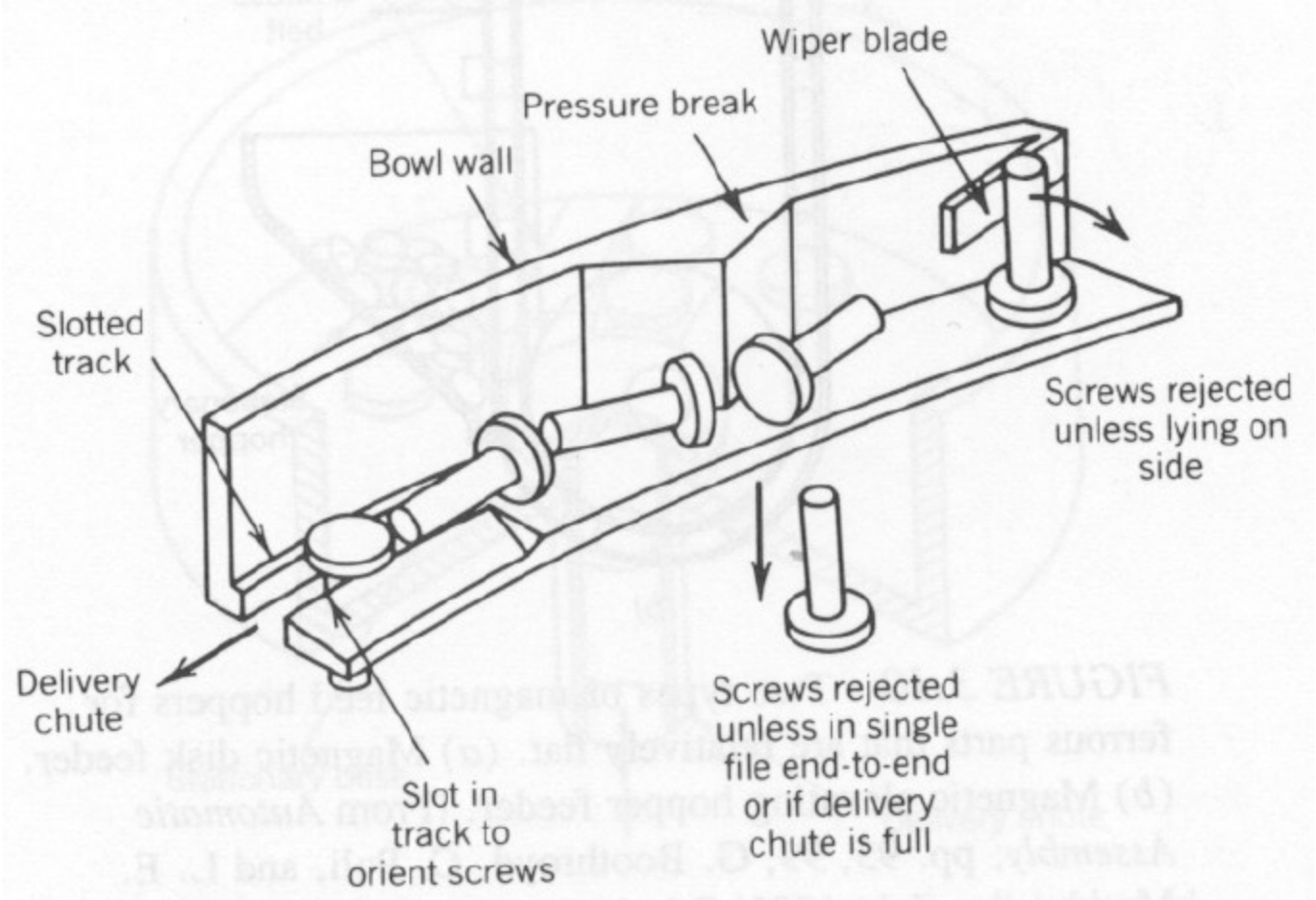
Gravity Feeders



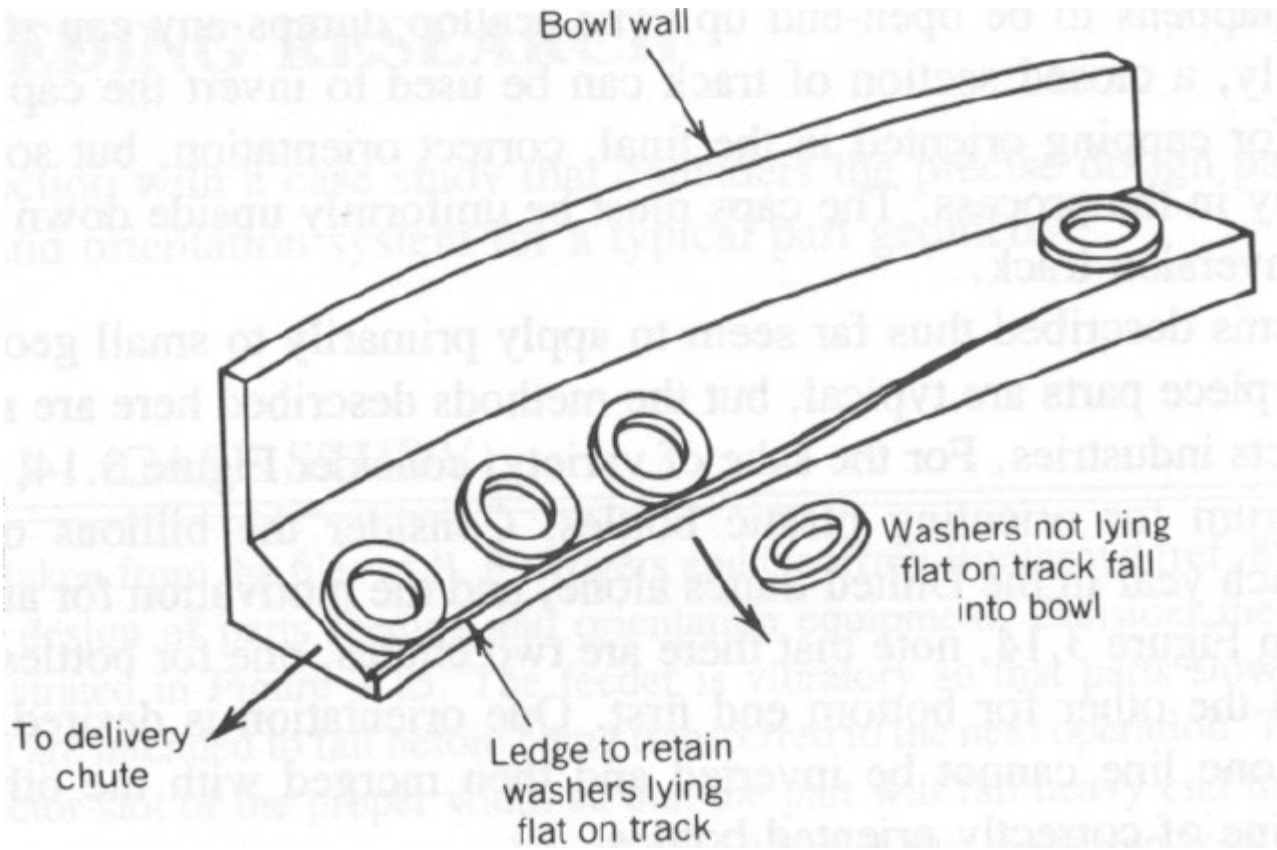
Bowl Feeders

Bowl Feeders

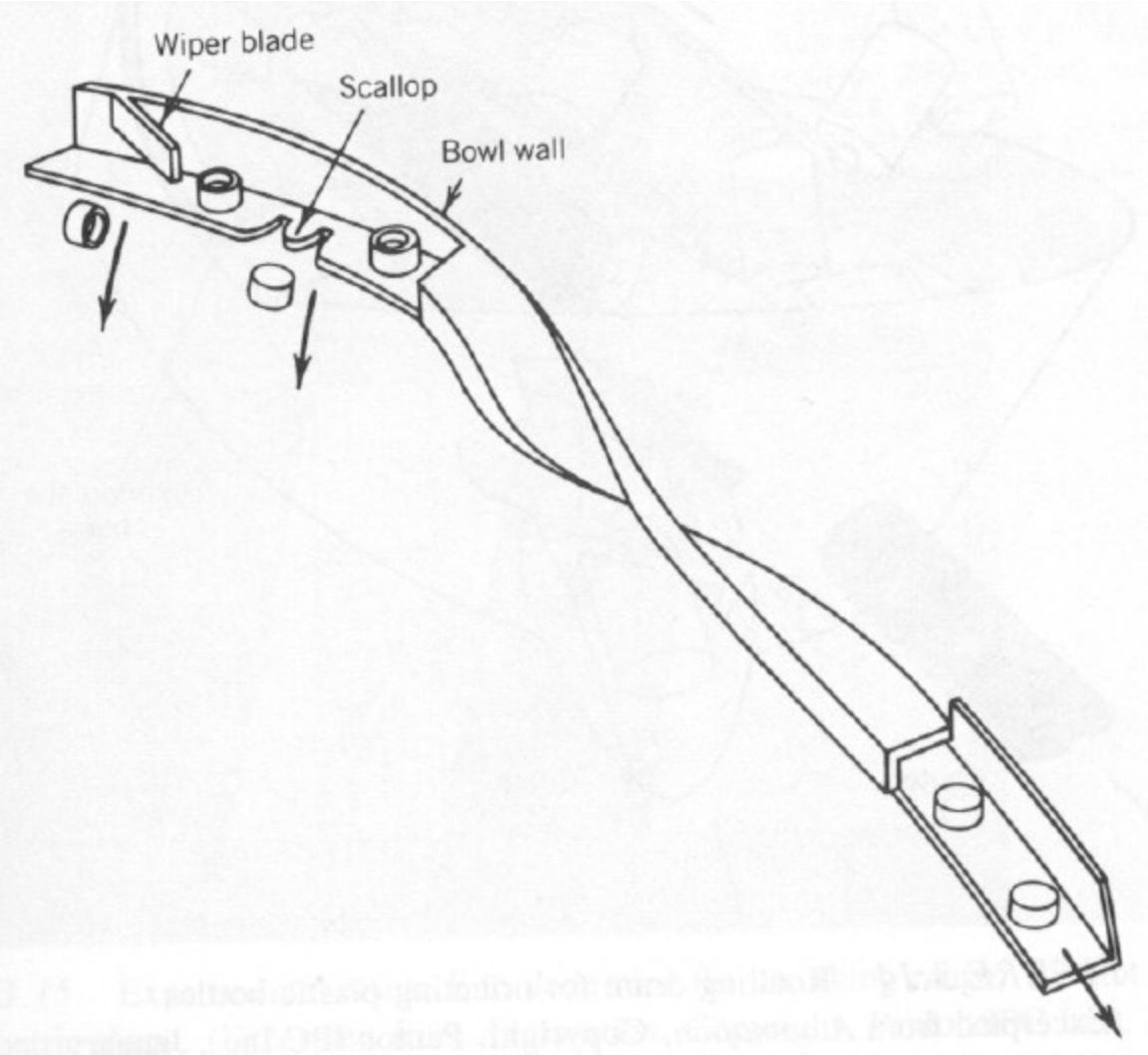
Bowl Feeders



Bowl Feeders



Bowl Feeders

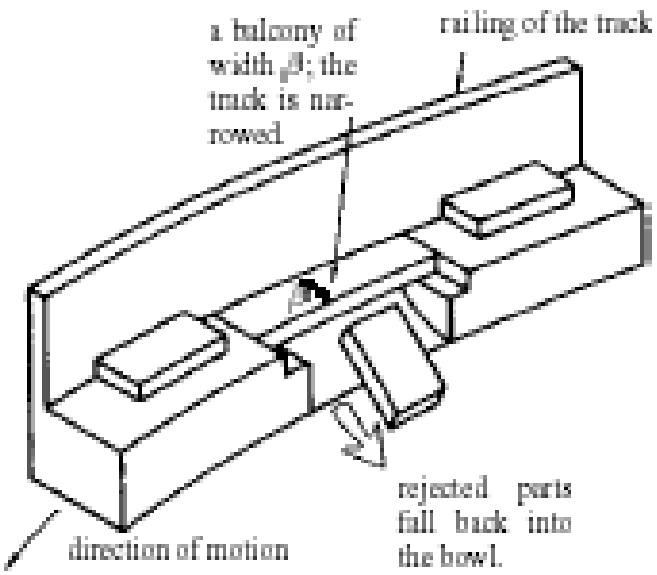


Bowl Feeders

- Design Factors
  - Part symmetry
  - Selector efficiency $E=F_o/F_i$
  - Recirculation effects

$$p_k = \left[\frac{E}{100}\right]\left[1-\frac{E}{100}\right]^k$$

Bowl Feeders - Trap Design



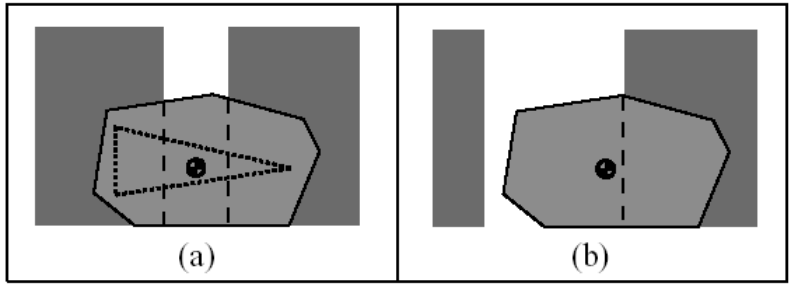


Figure 2: (a) A safe pose. The triangle is evidence of safeness. (b) An unsafe pose of the same part above a different trap.

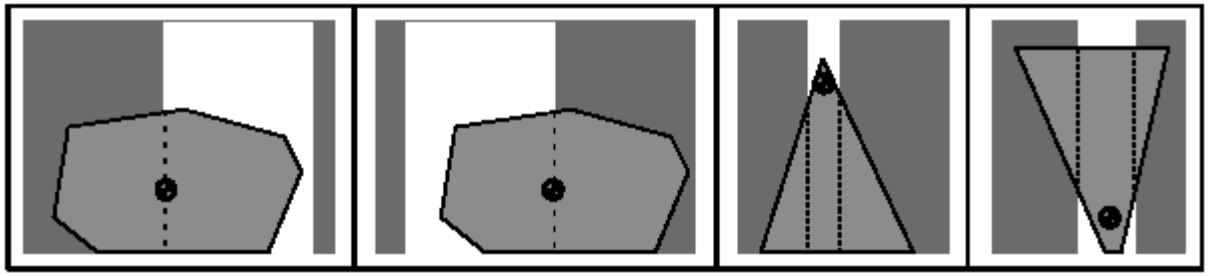


Figure 4: The types of rejected poses.

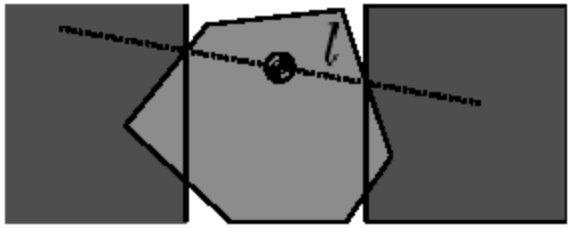
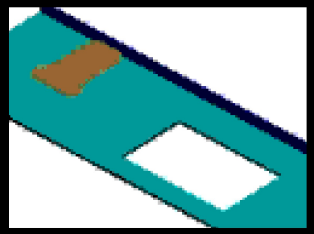
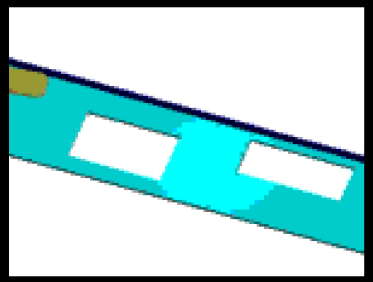
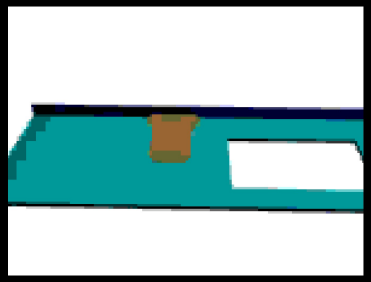


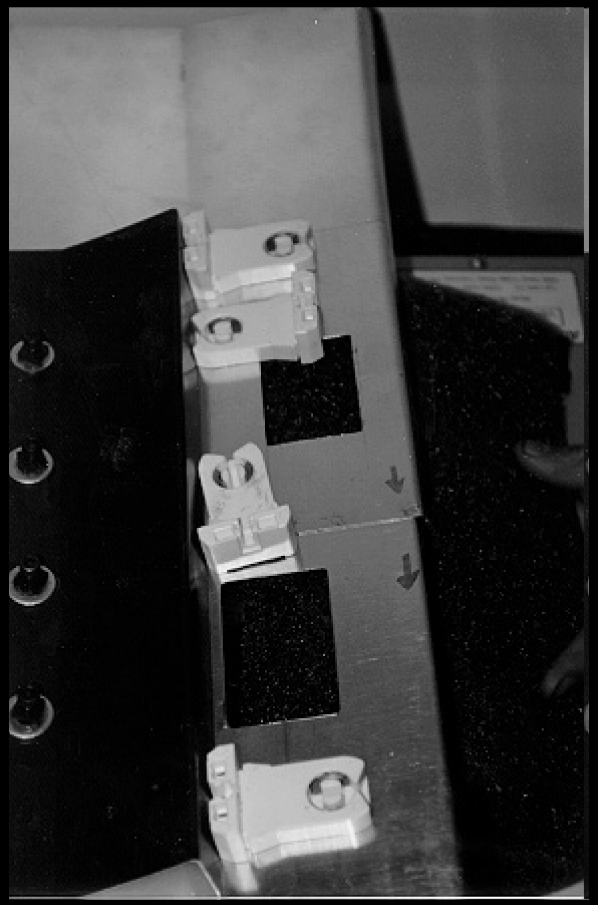
Figure 5: A critical pose.

Bowl Feeders - Trap Design









Non-vibrating Feeders

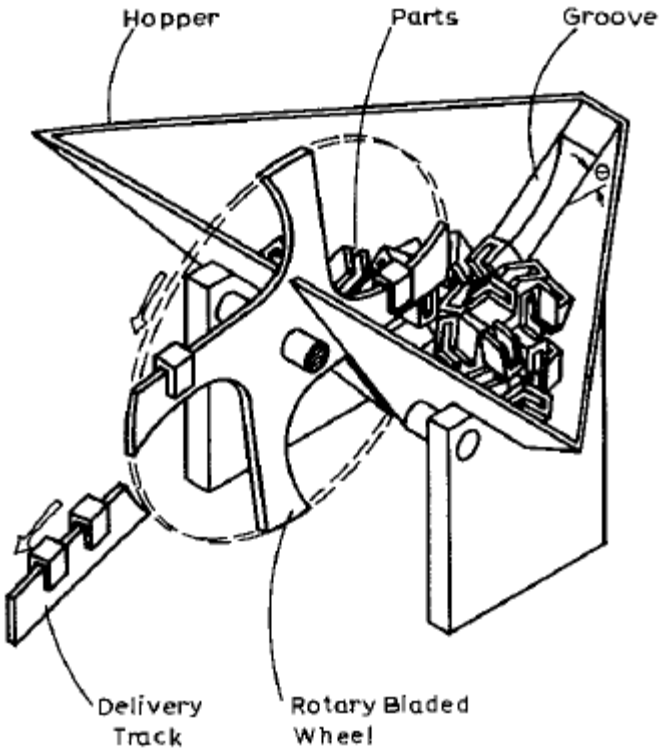
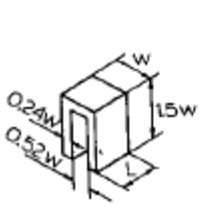
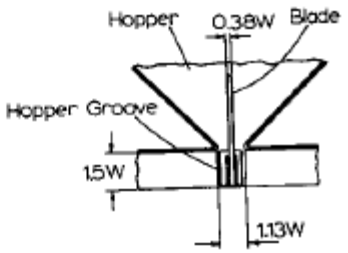
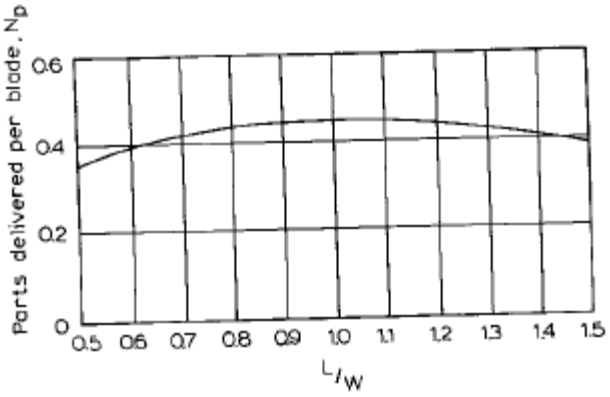


Fig. 4.34 Rotary centerboard hopper.







Non-vibrating Feeders

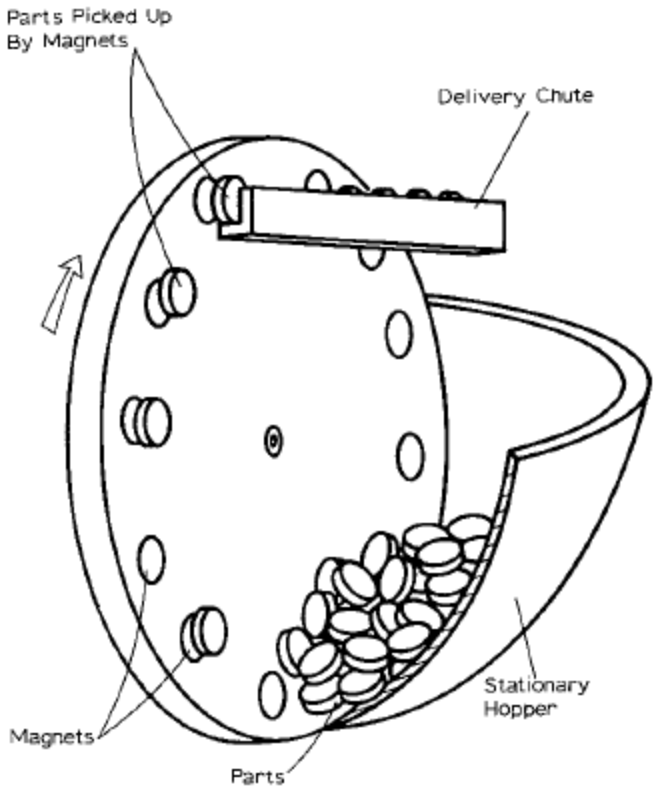
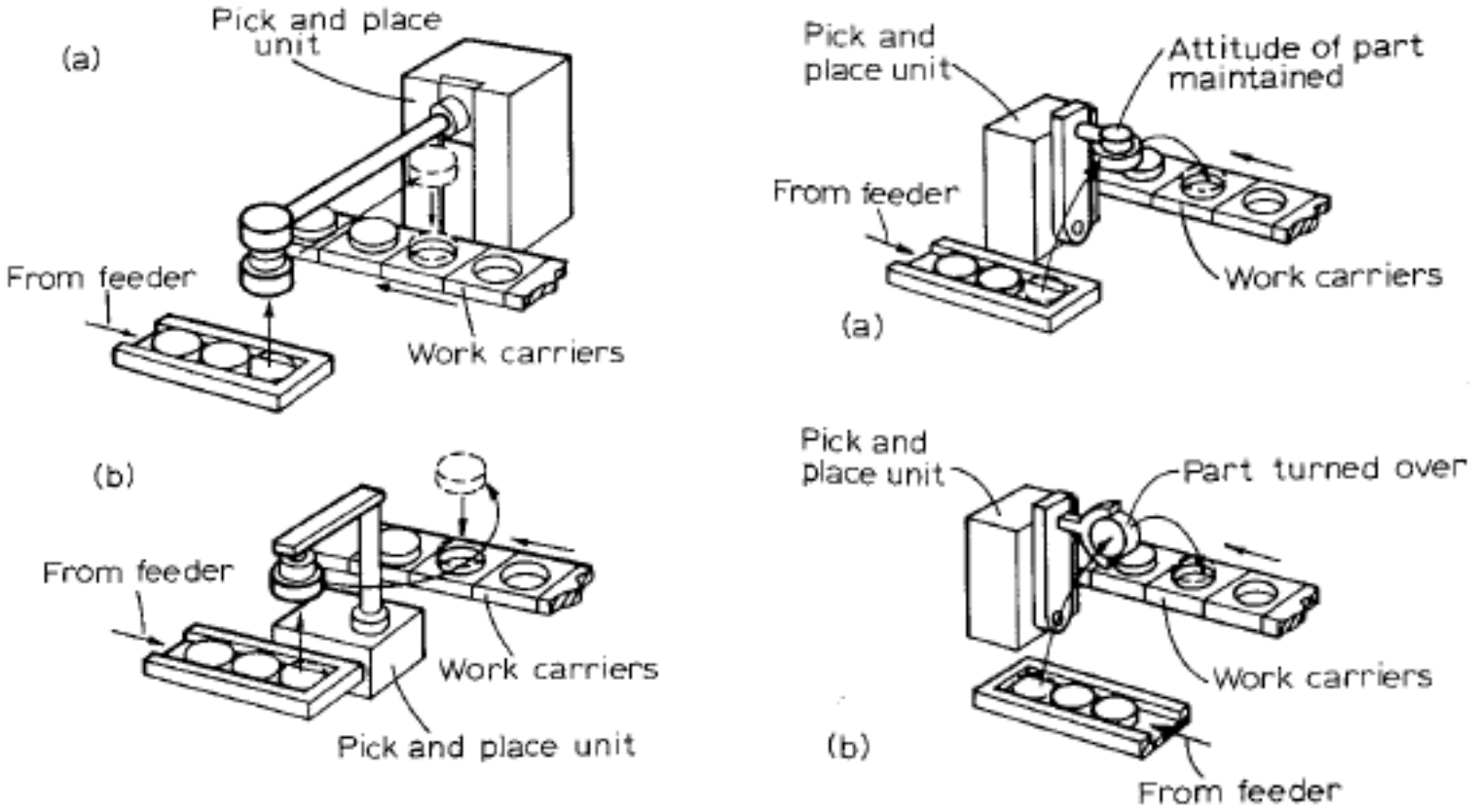
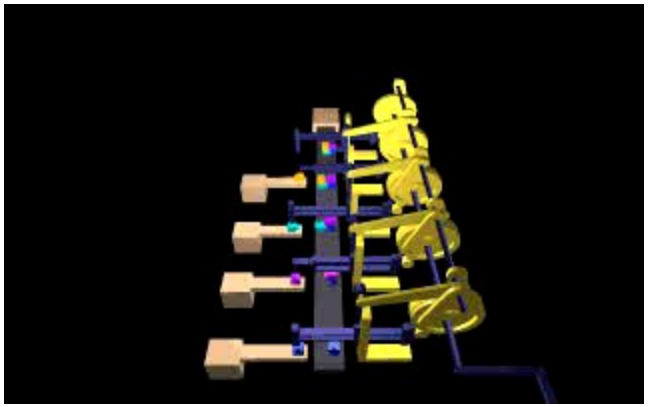


Fig. 4.36 Magnetic-disk feeder.

Pick & Place

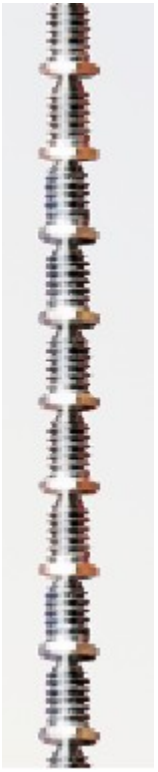

(a)
Pick and place unit
From feeder
Work carriers
(b)
From feeder
Work carriers
Pick and place unit
Pick and place unit
Attitude of part maintained
From feeder
Work carriers
(a)
Pick and place unit
Part turned over
Work carriers
(b)
From feeder

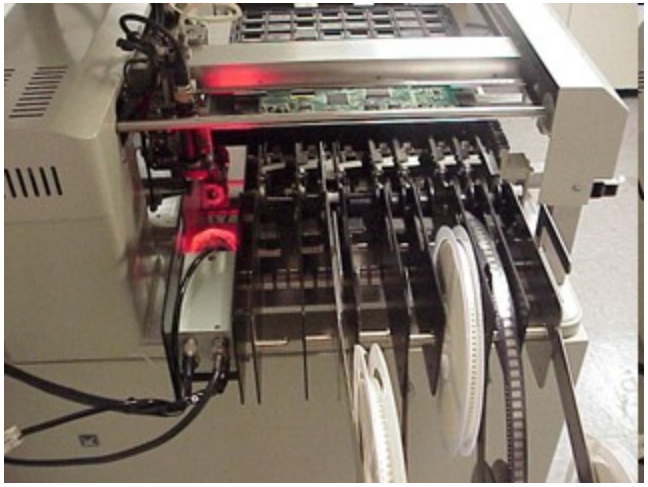
Pick & Place




L SERIES
MODEL L60
Board sizes to 13.5 x 32"
& 96 feeder positions

Pre-collated Components

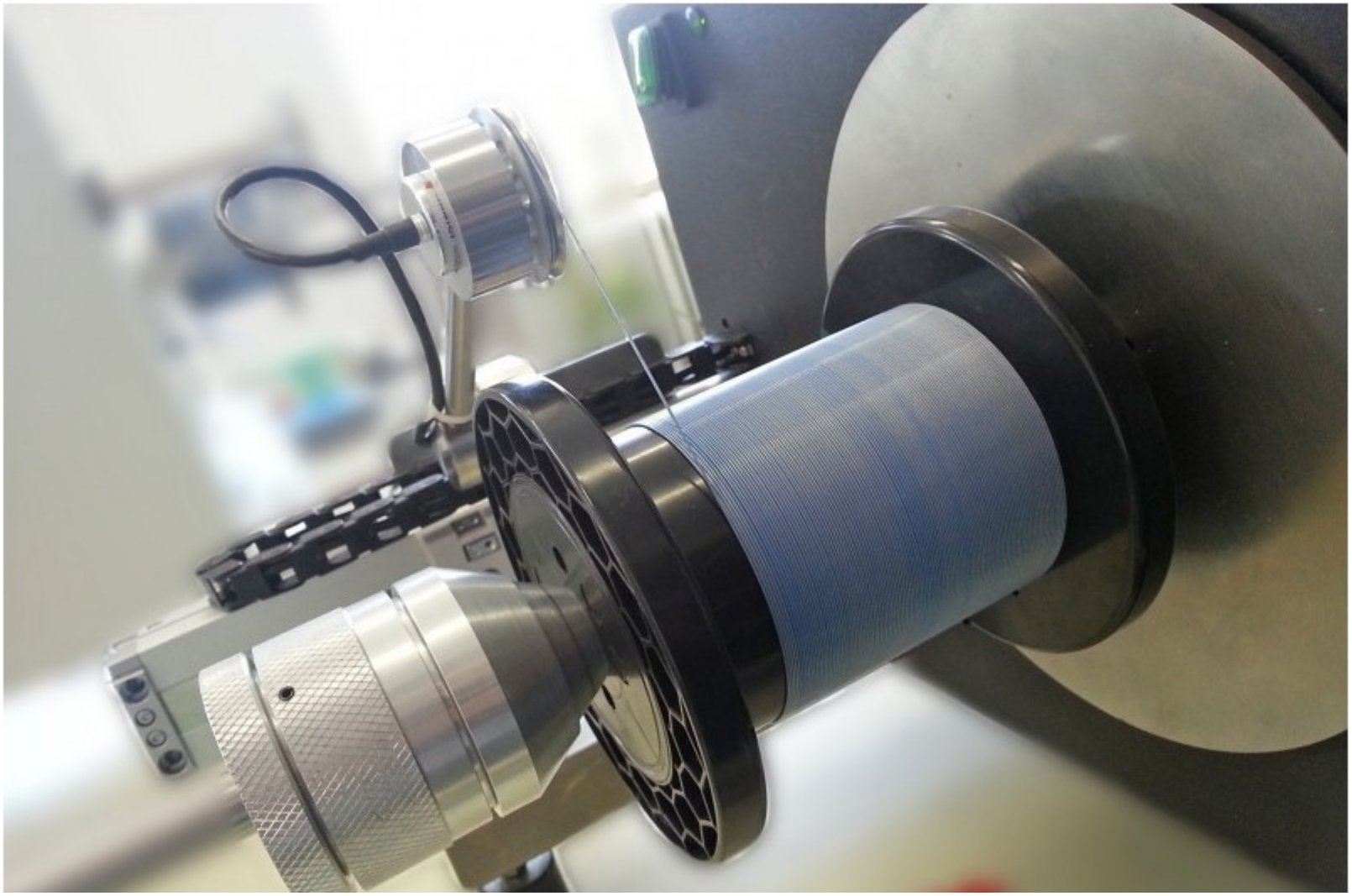




Feeding Flexible Line

Feeding Flexible Line

Feeding Flexible Line



Feeding Flexible Line