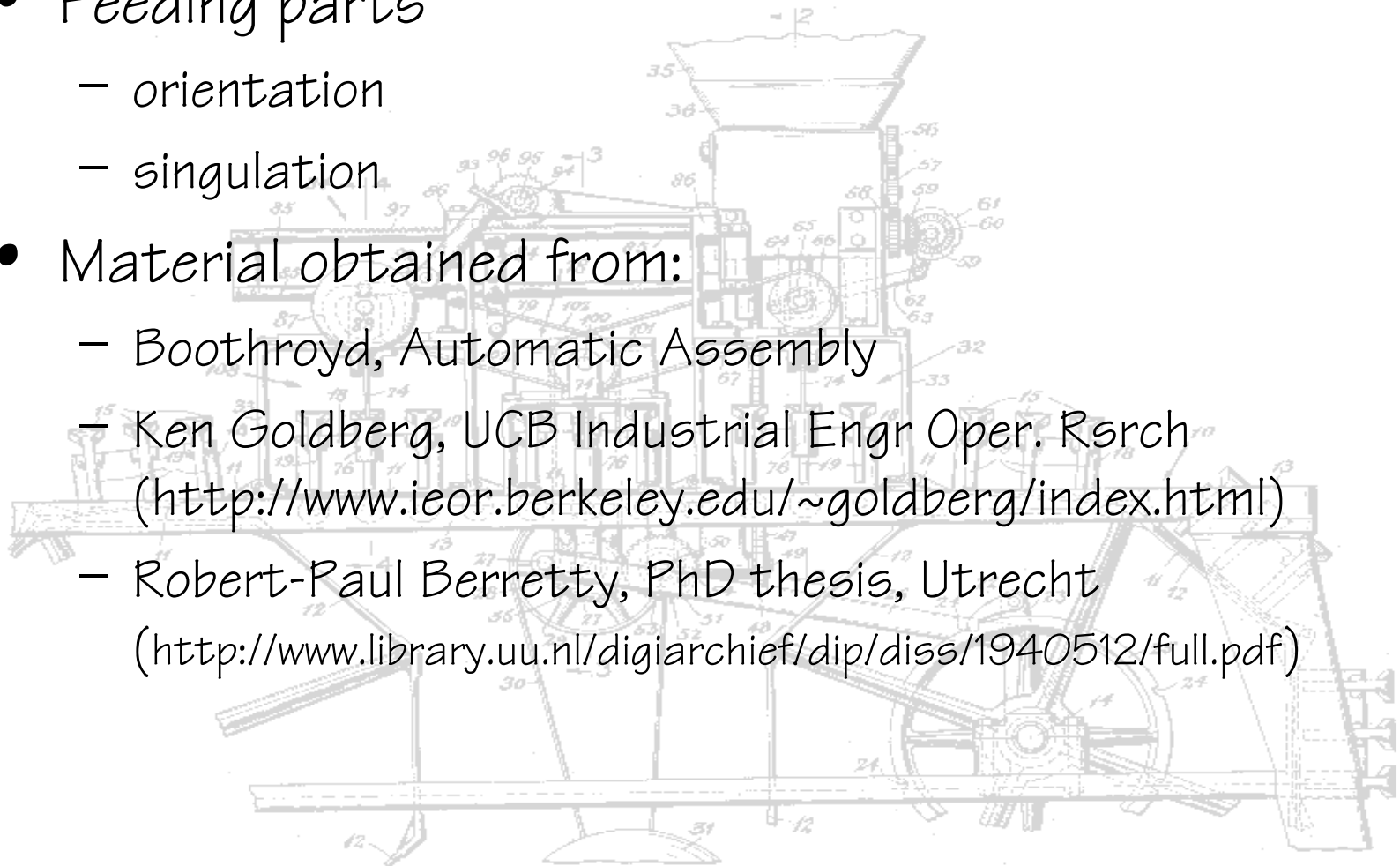


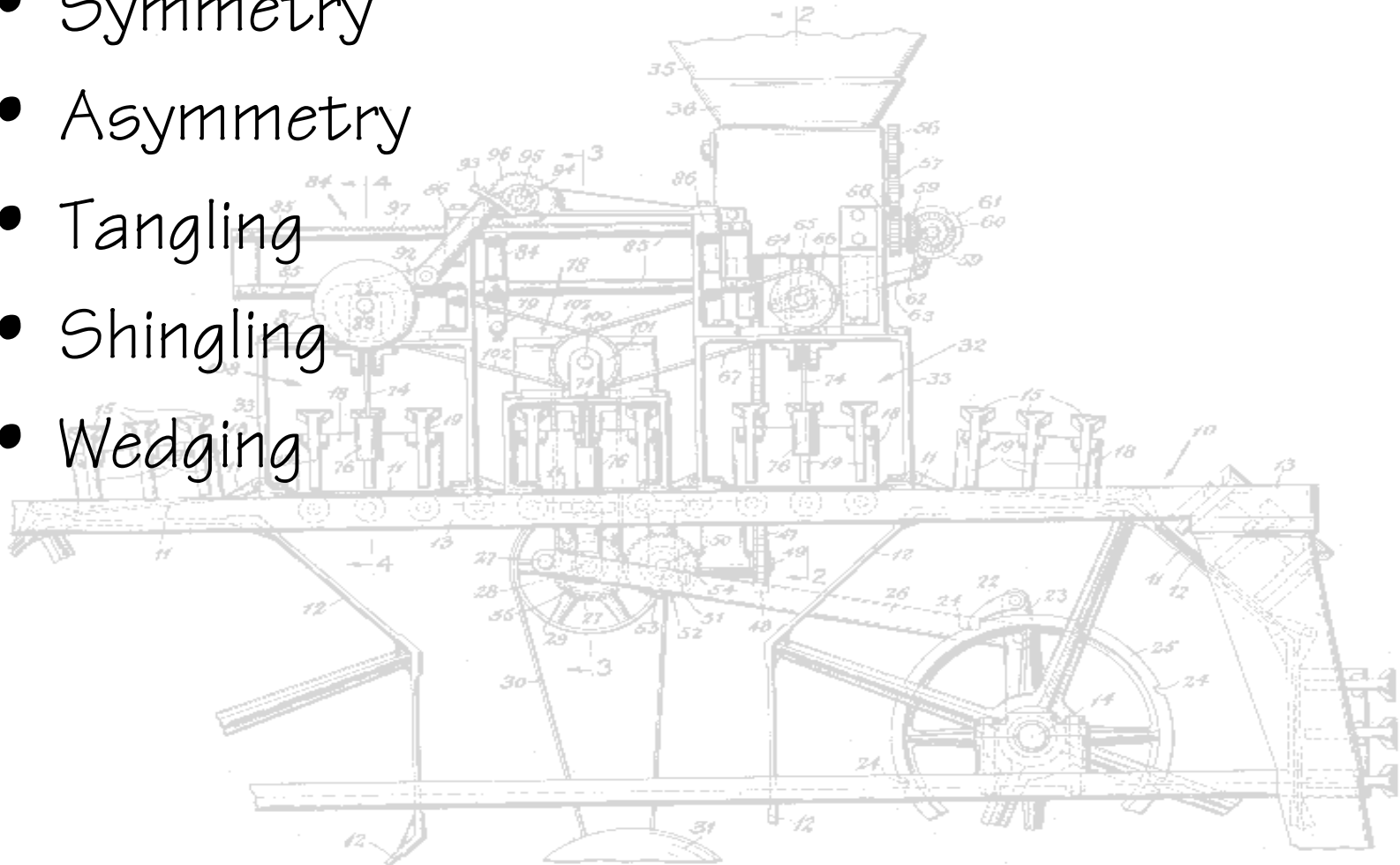
CARE & FEEDING OF MACHINES

- Feeding parts
 - orientation
 - singulation
- Material obtained from:
 - Boothroyd, Automatic Assembly
 - Ken Goldberg, UCB Industrial Engr Oper. Rsrch (<http://www.ieor.berkeley.edu/~goldberg/index.html>)
 - Robert-Paul Berretty, PhD thesis, Utrecht (<http://www.library.uu.nl/digiarchief/dip/diss/1940512/full.pdf>)

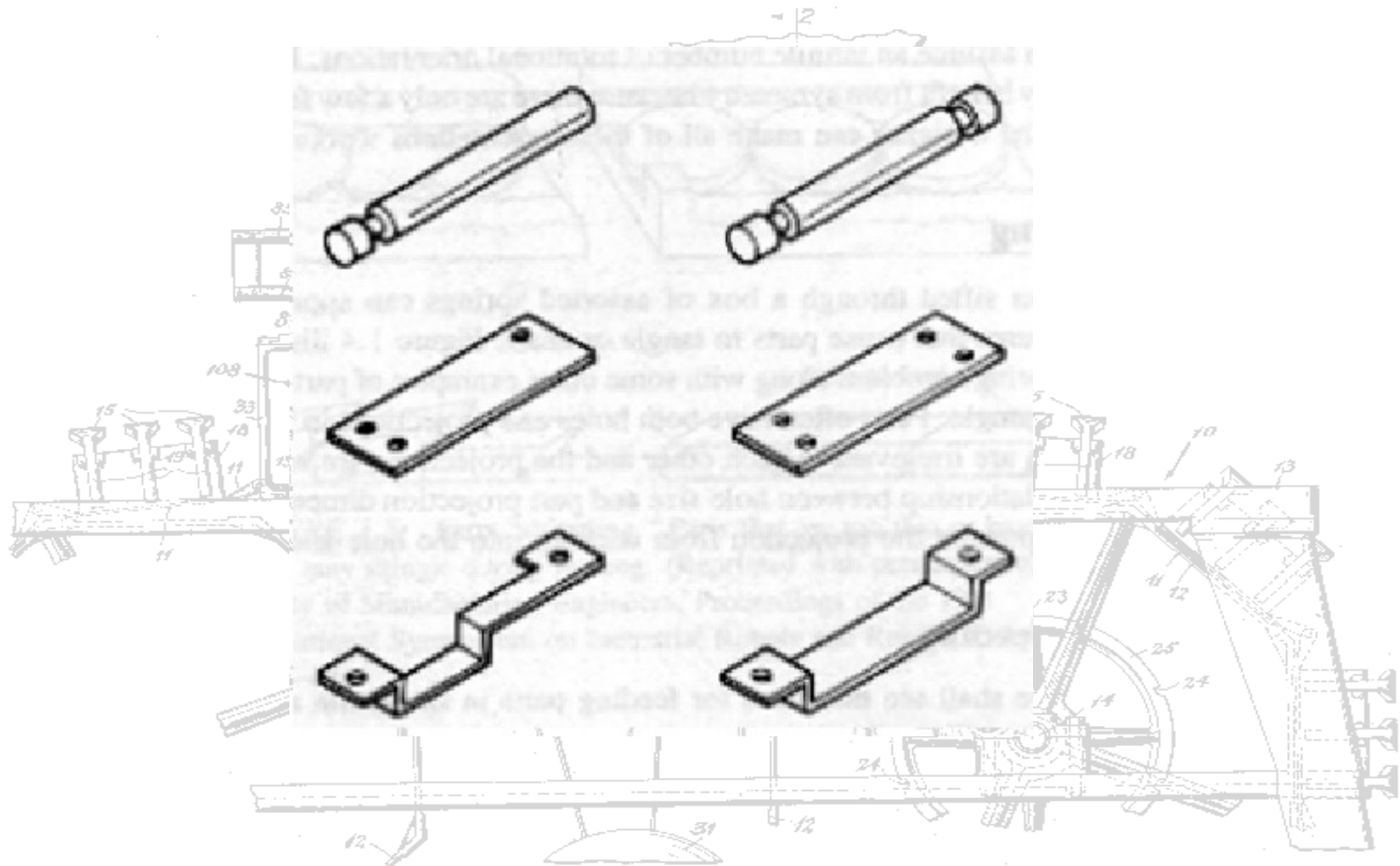


DESIGNING PARTS FOR FEEDING

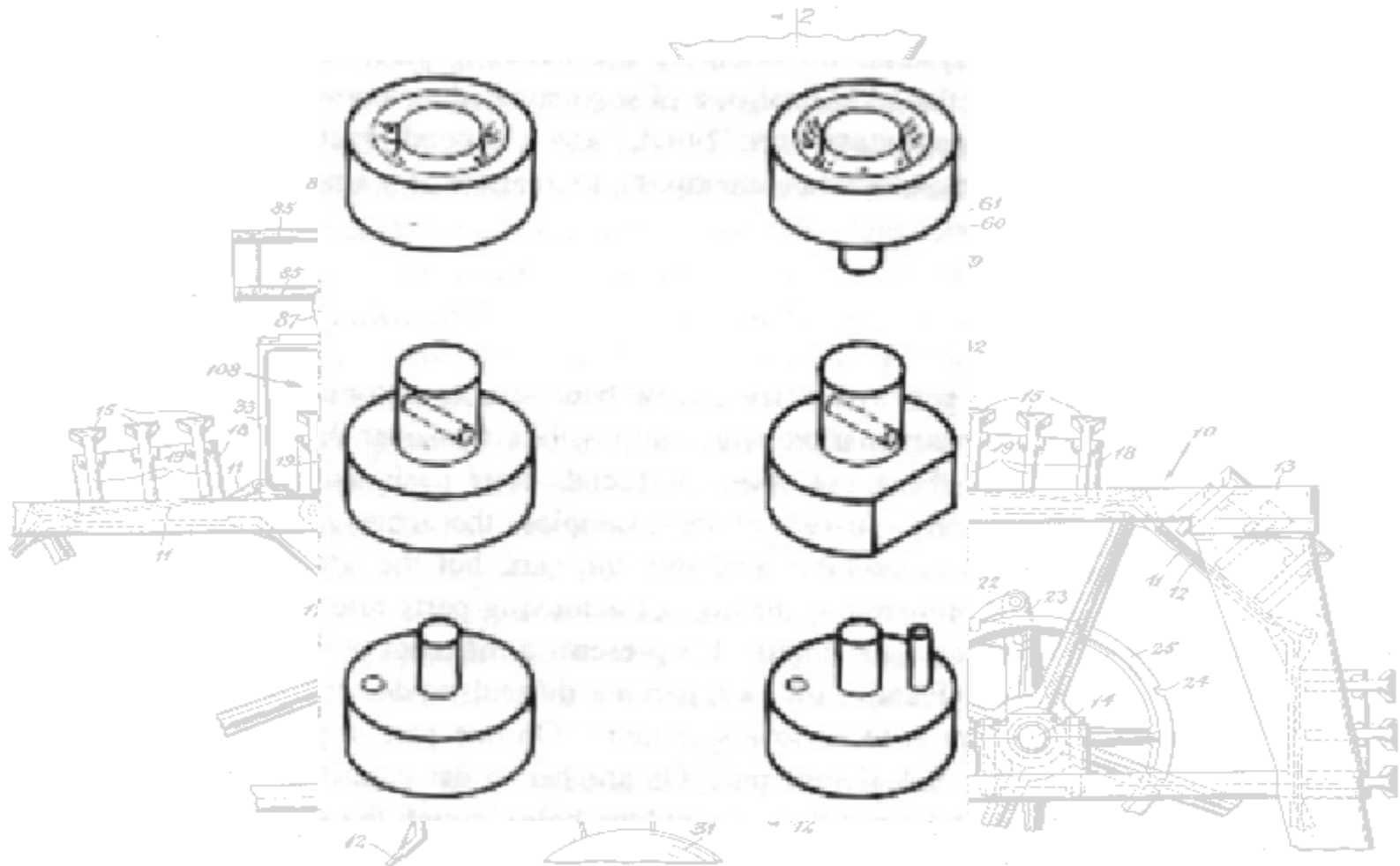
- Symmetry
- Asymmetry
- Tangling
- Shingling
- Wedging



SYMMETRY



ASYMMETRY

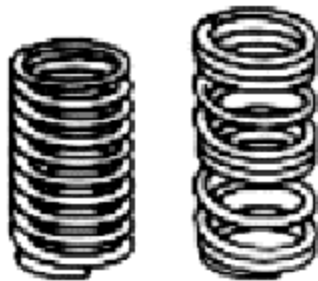


TANGLING

Difficult to feed



Preferred



Opening less than wire diameter prevents nesting

Difficult to feed



Preferred



Open ends



Closed ends



Tight coils prevent nesting

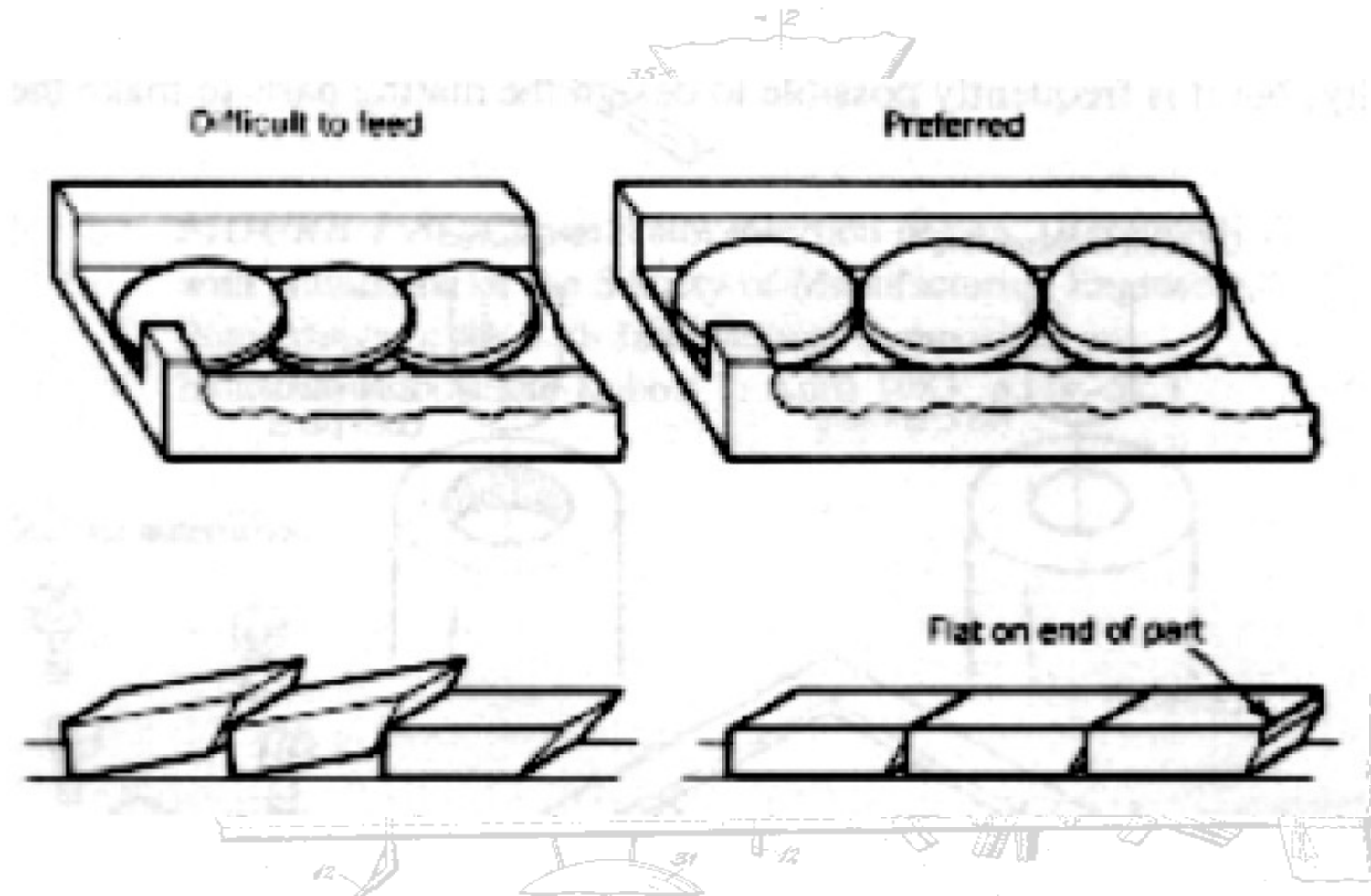
Larger tab



Smaller hole

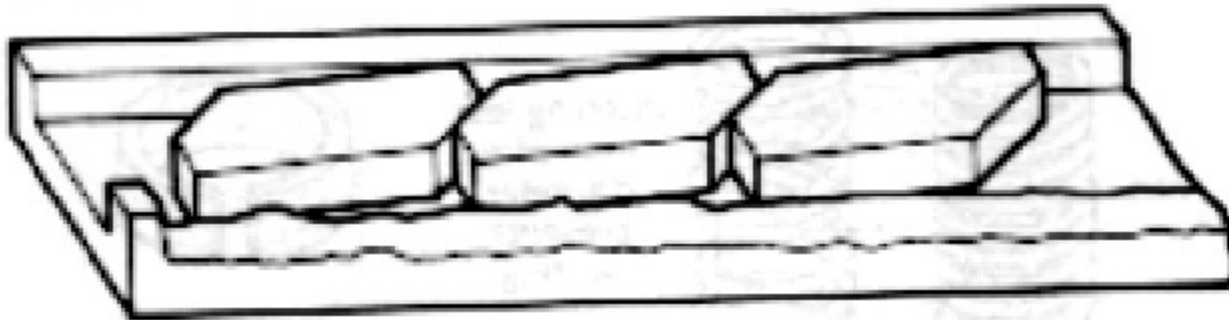


SHINGLING

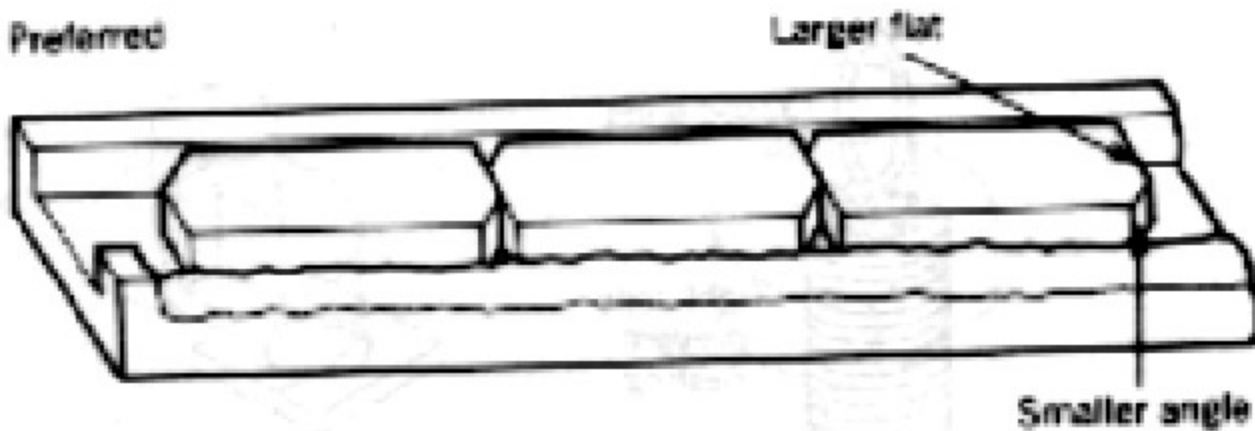


WEDGING

Difficult to feed

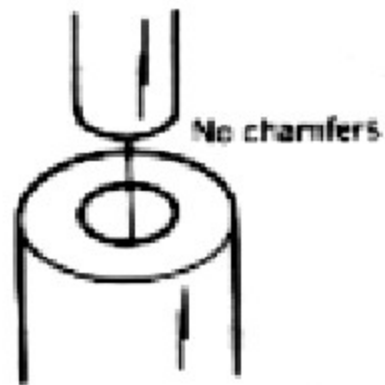


Preferred

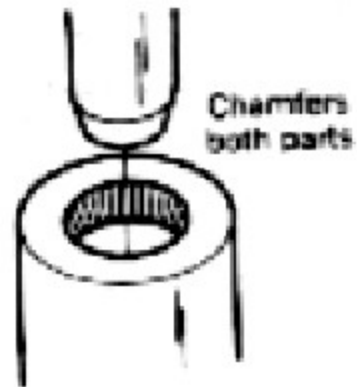


DESIGNING FOR INSERTION

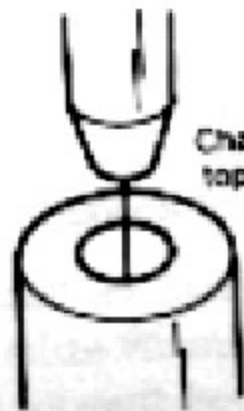
Difficult to assemble



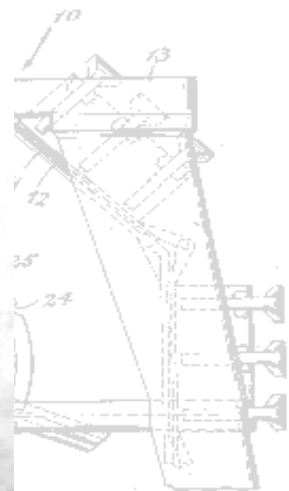
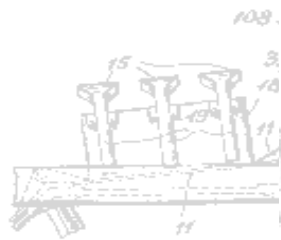
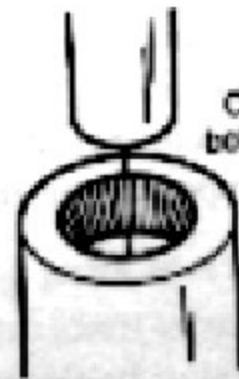
Preferred



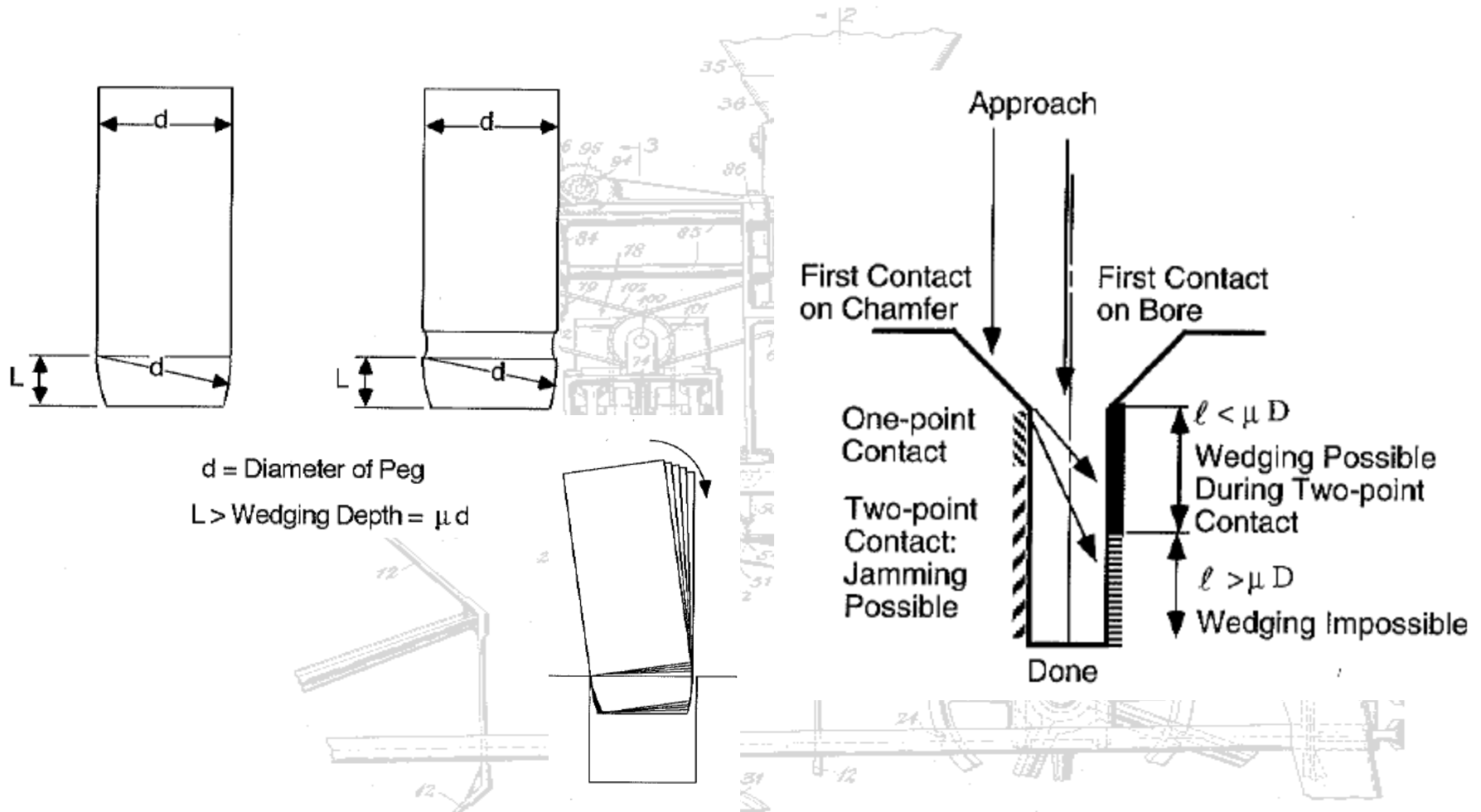
Chamfer top part



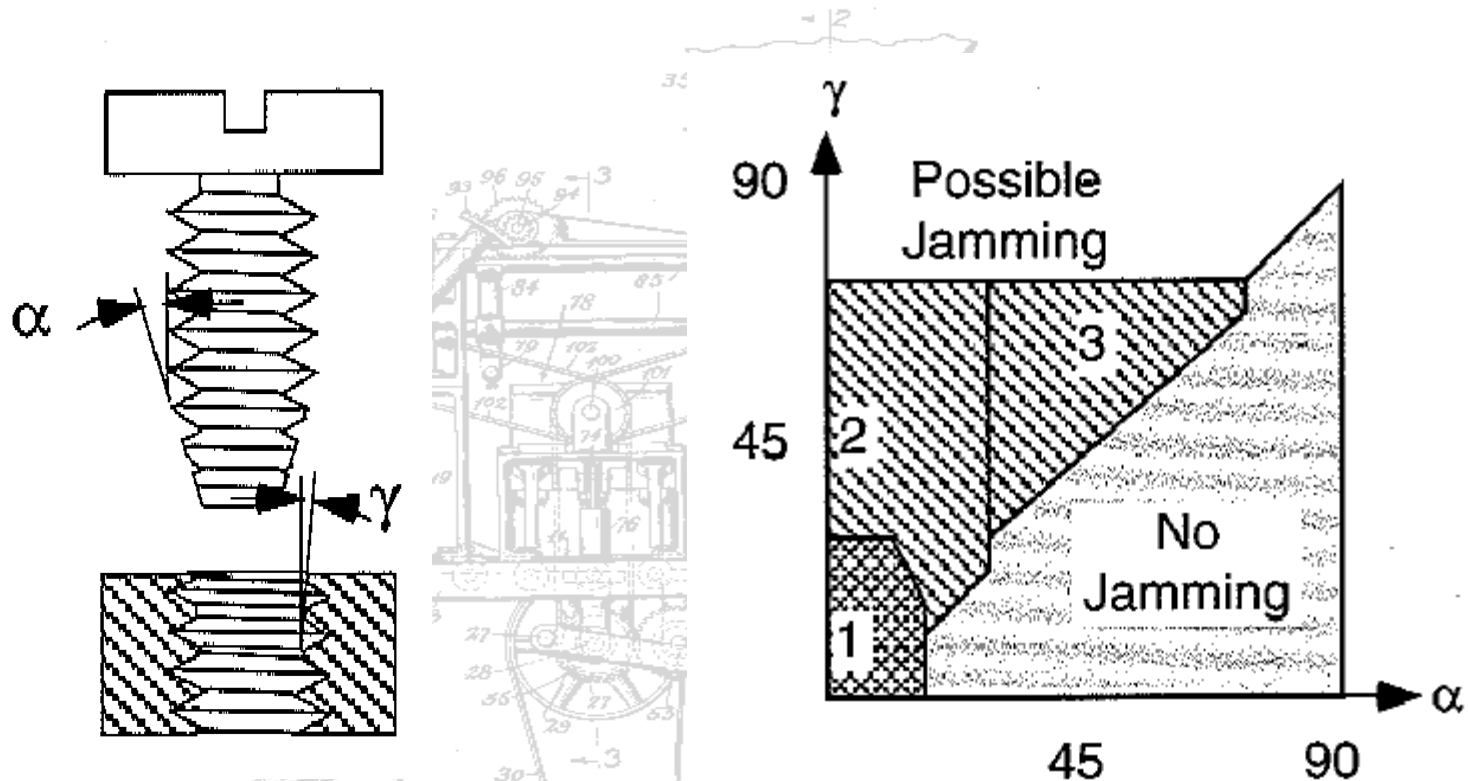
Chamfer bottom part



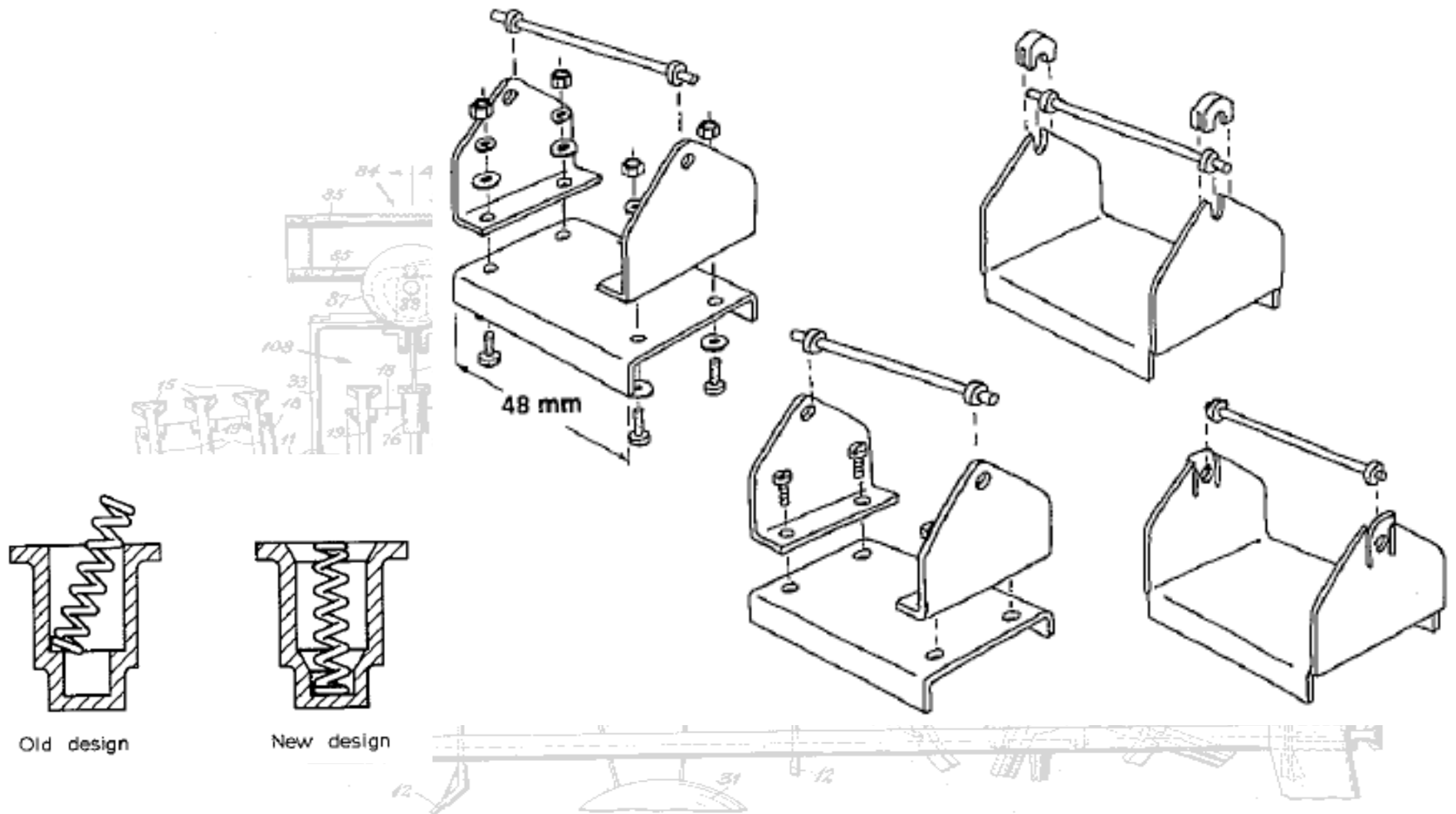
INSERTING PEGS IN ROUND HOLES



SCREW THREAD MATING

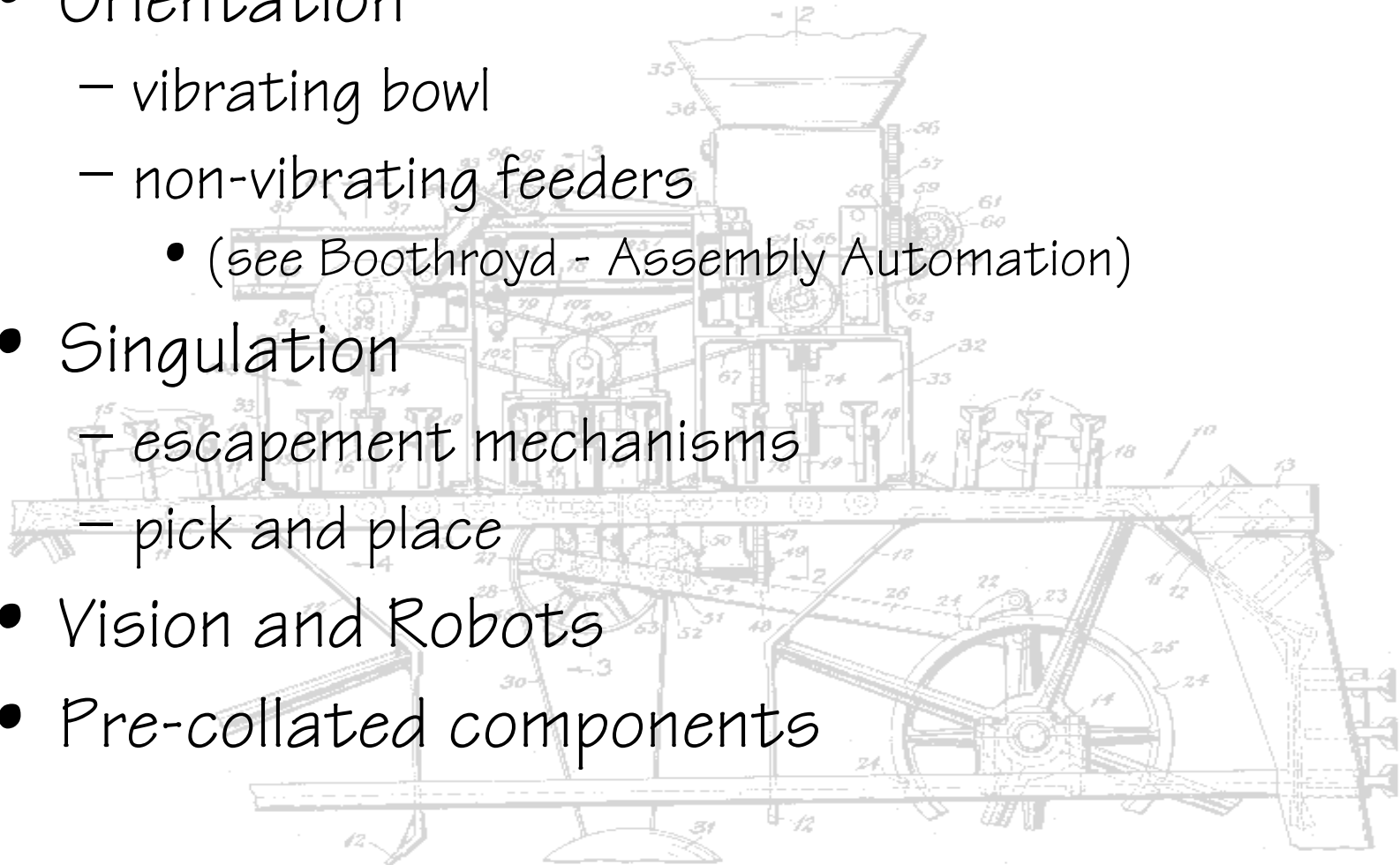


SIMPLIFYING THE DESIGN



FASTENER FEEDING REQUIREMENTS

- Orientation
 - vibrating bowl
 - non-vibrating feeders
 - (see Boothroyd - Assembly Automation)
- Singulation
 - escapement mechanisms
 - pick and place
- Vision and Robots
- Pre-collated components



SINGULATION

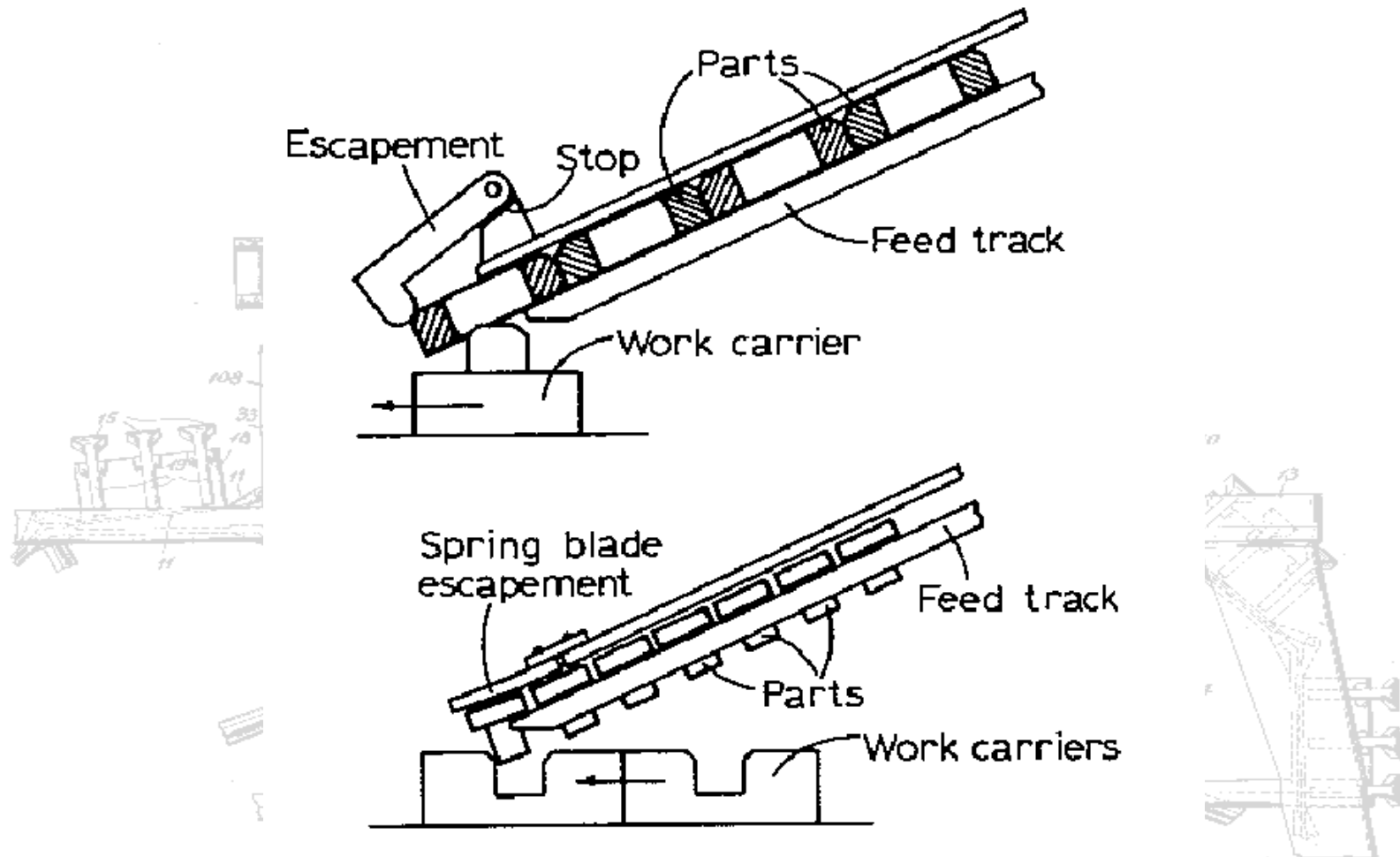


Fig. 5.24 Escapements actuated by the work carrier.

SINGULATION

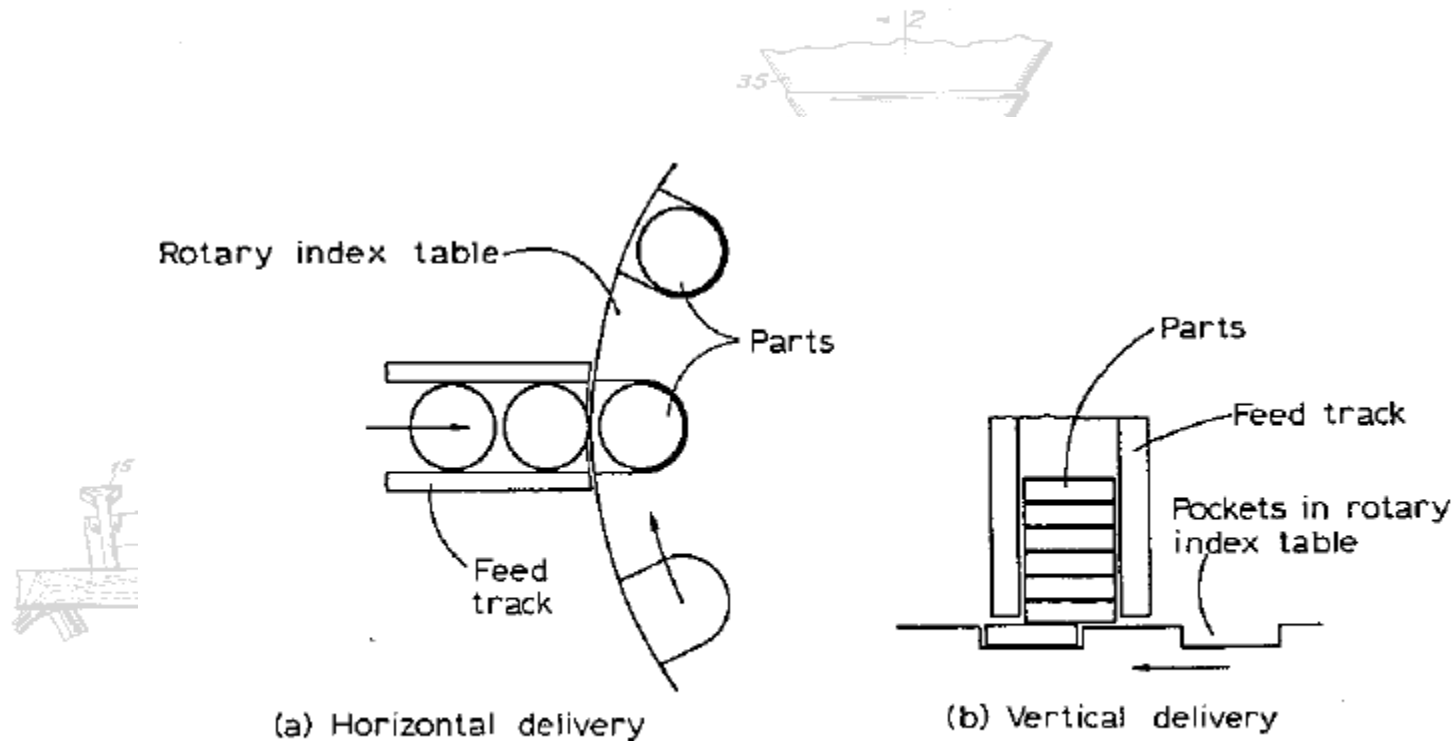
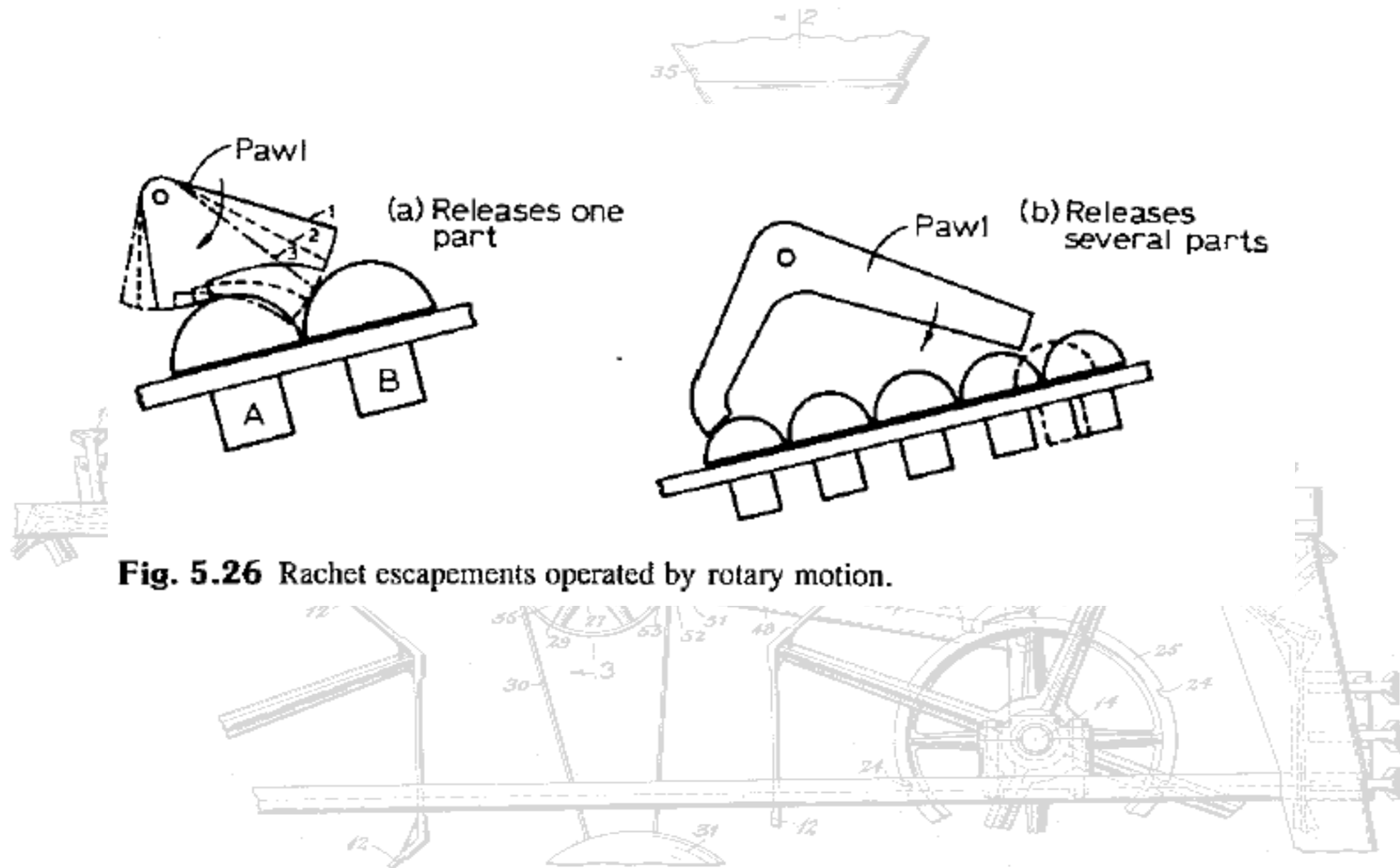


Fig. 5.25 Feeding of parts onto rotary index table.

SINGULATION



SINGULATION

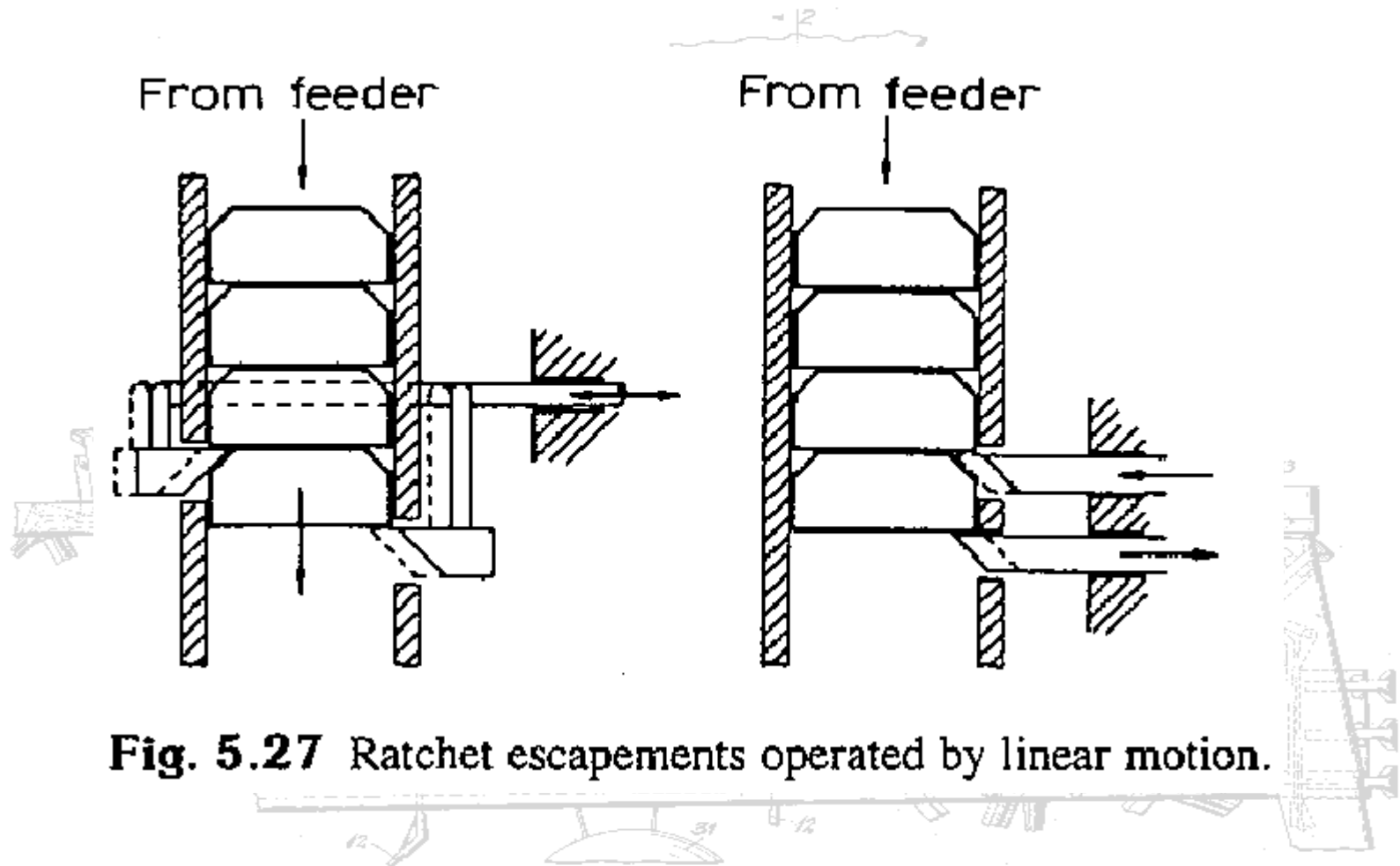
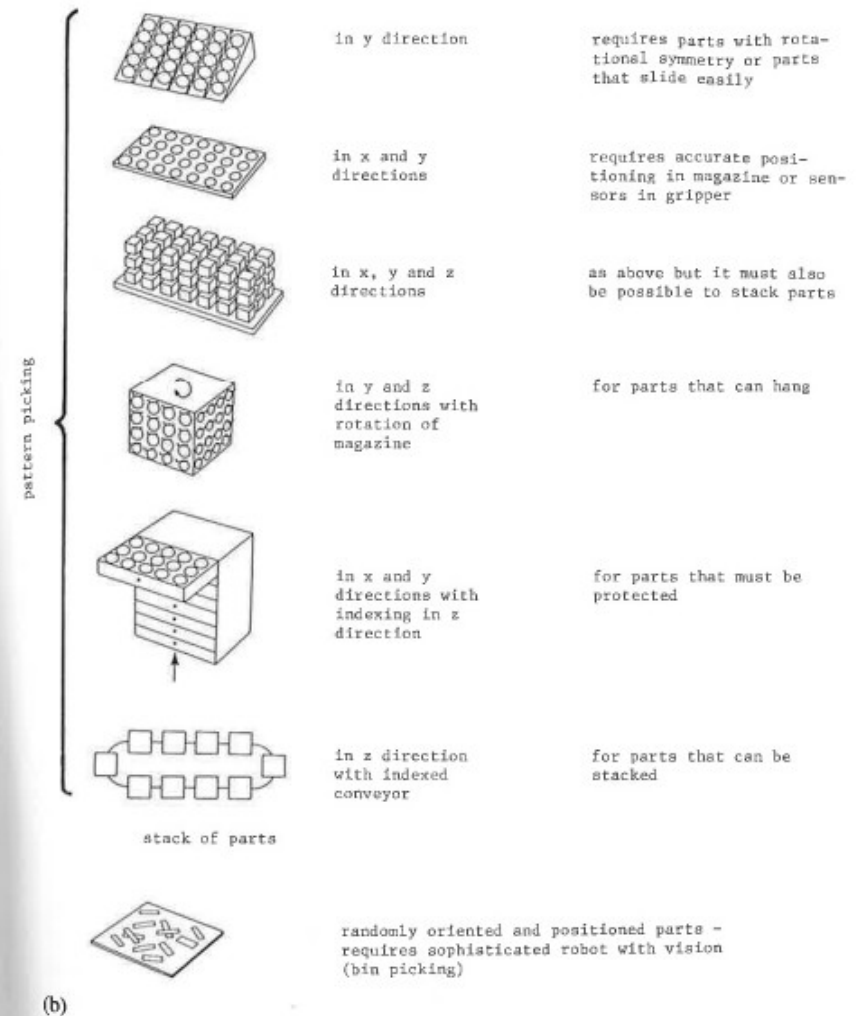
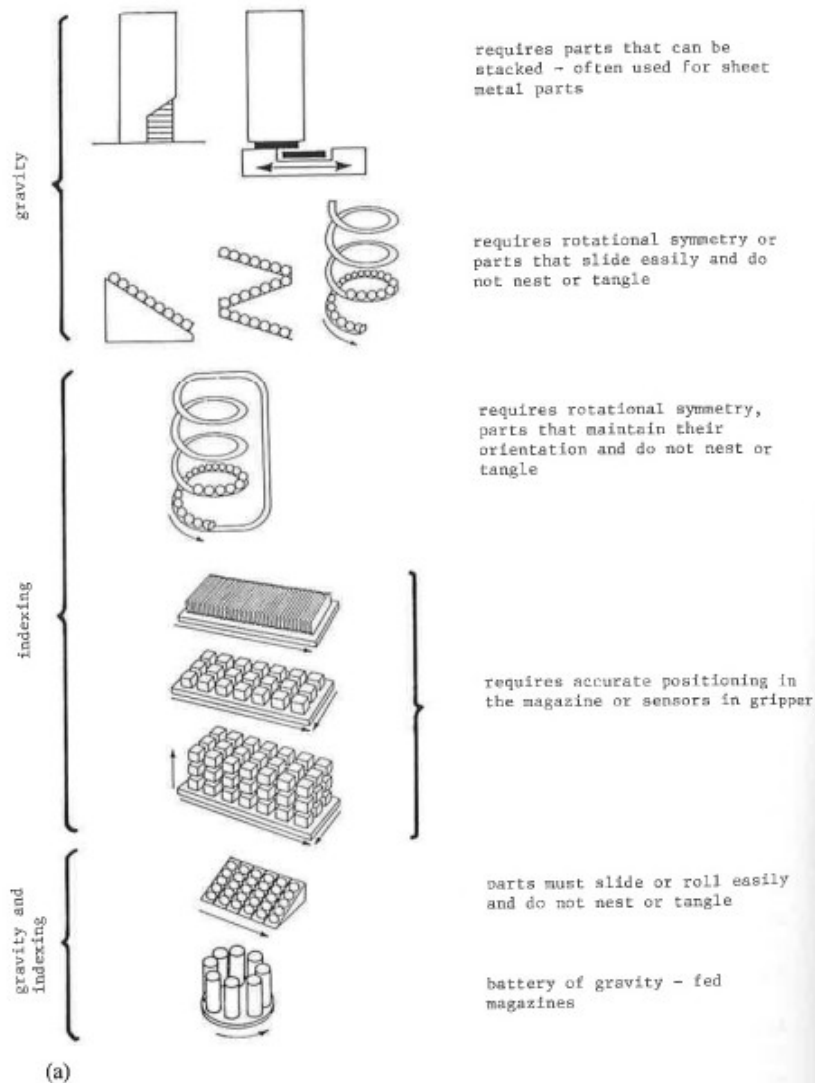
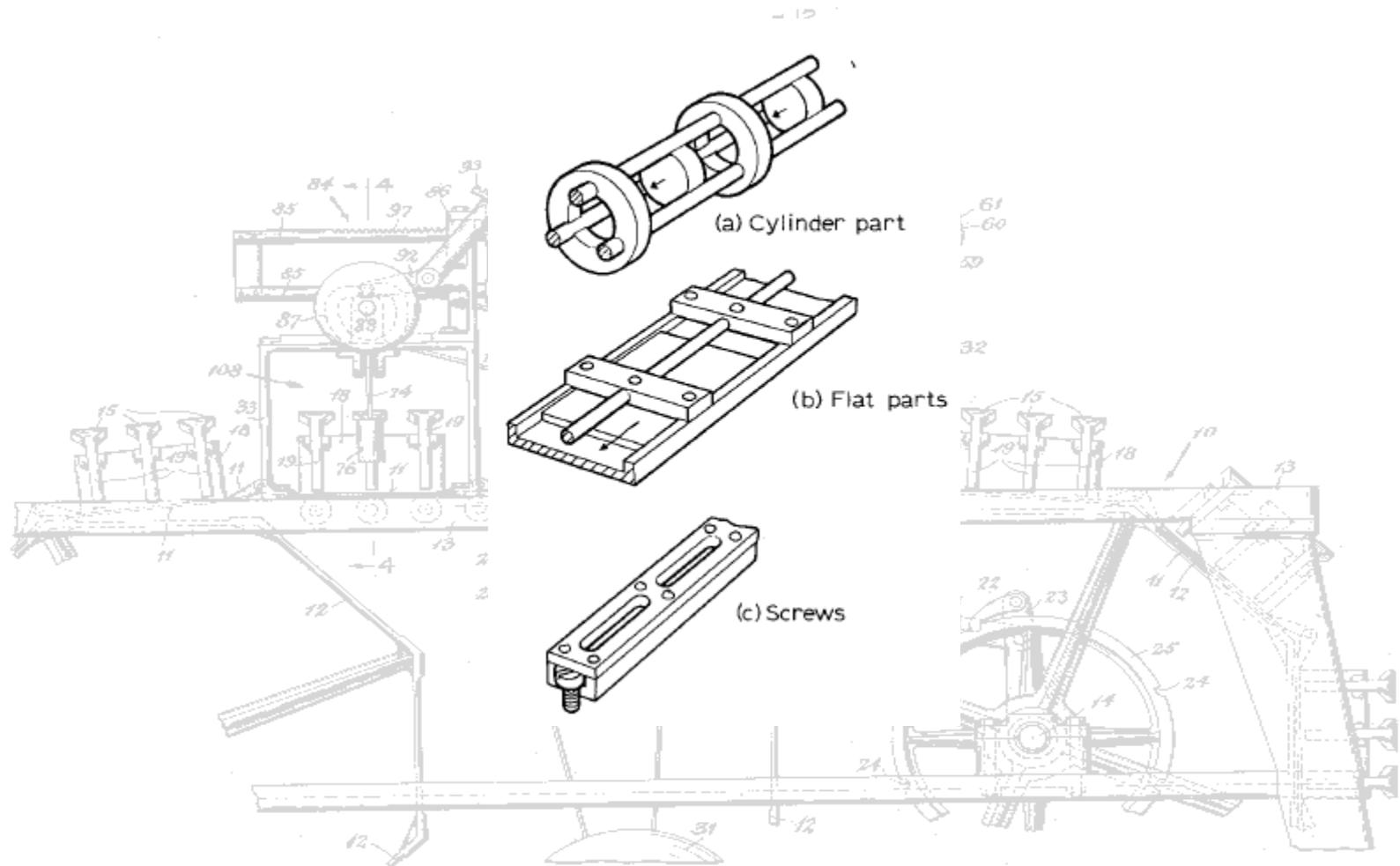


Fig. 5.27 Ratchet escapements operated by linear motion.

VARIETY OF FEEDING METHODS



GRAVITY FEEDERS



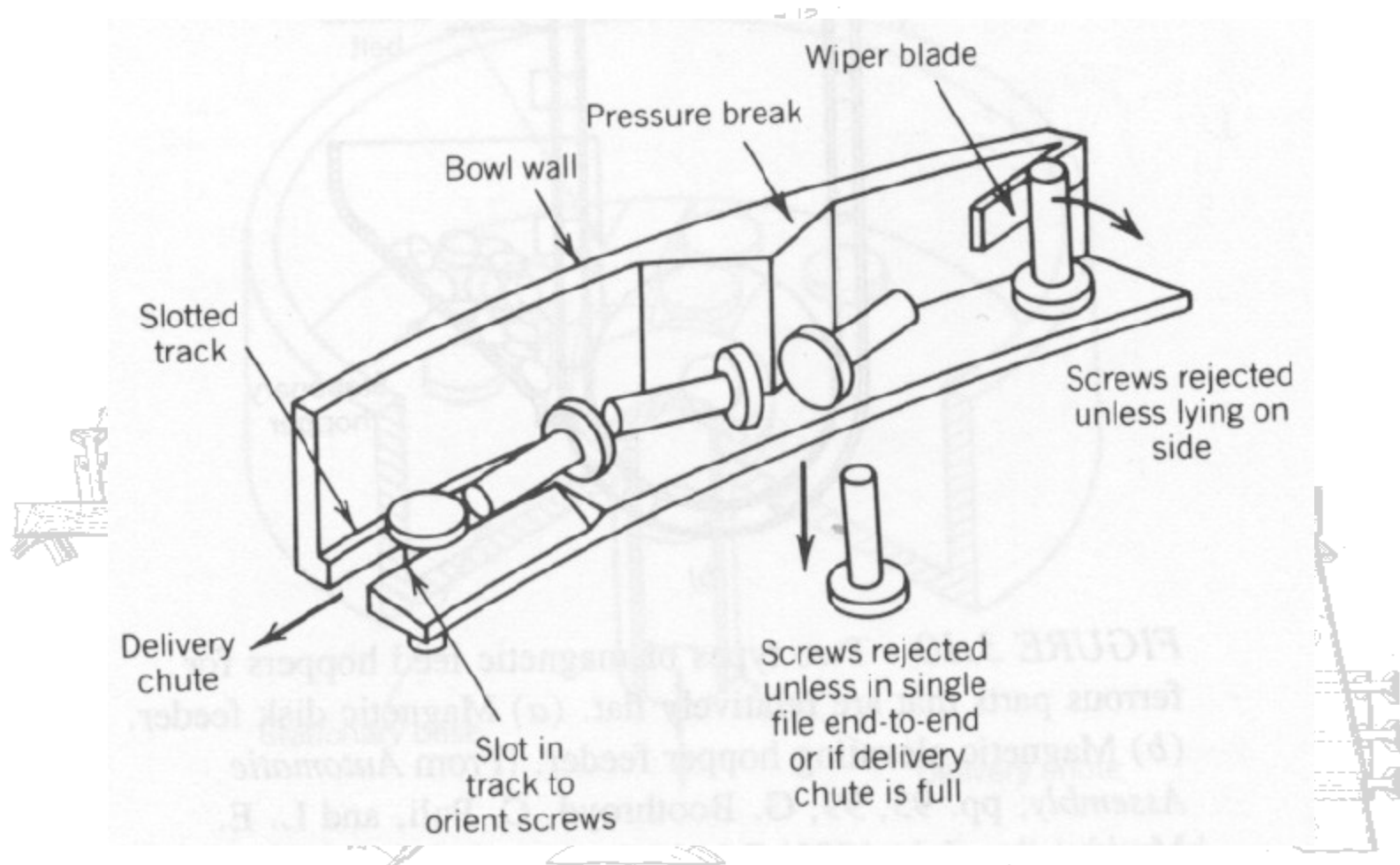
BOWL FEEDERS



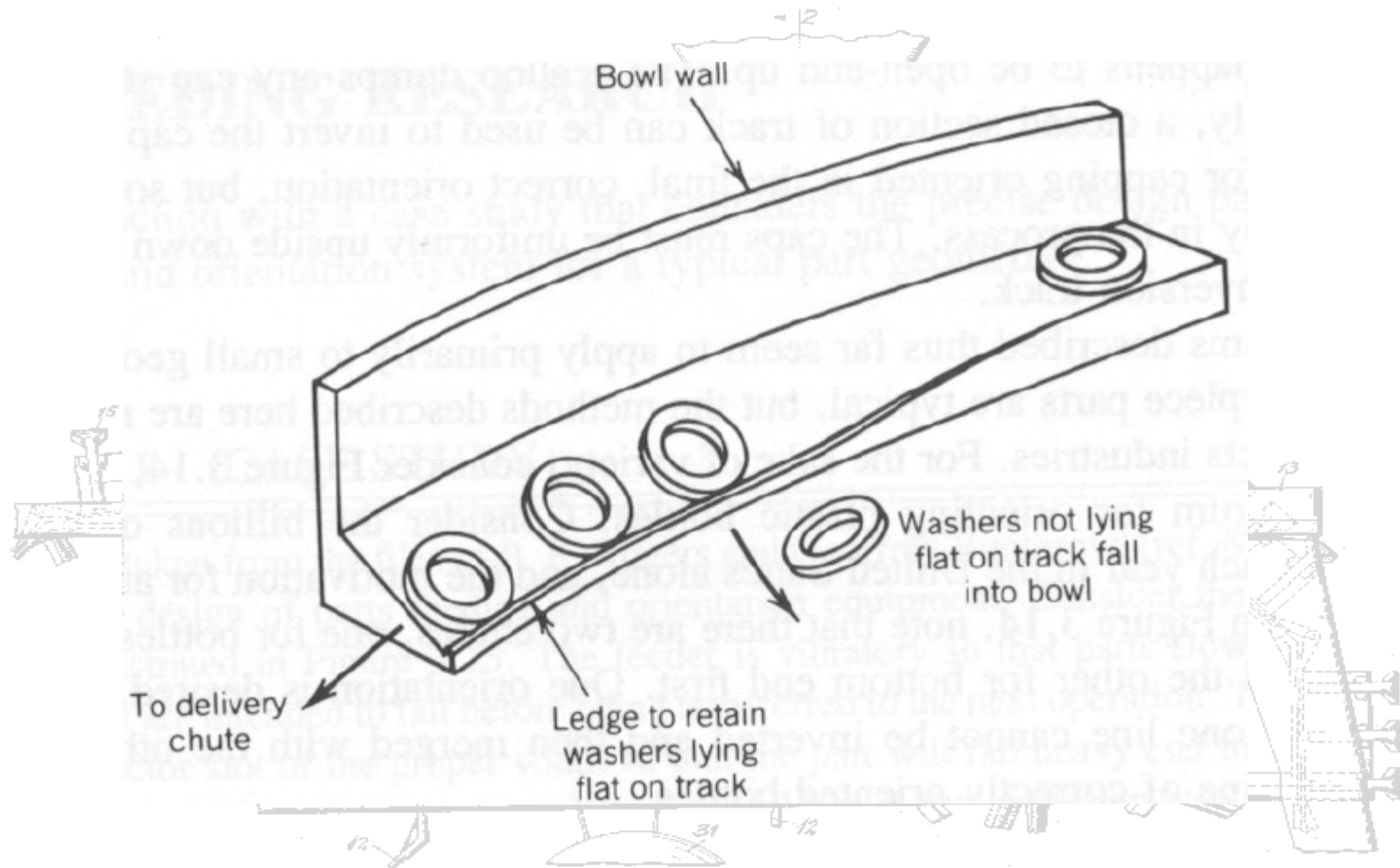
BOWL FEEDERS



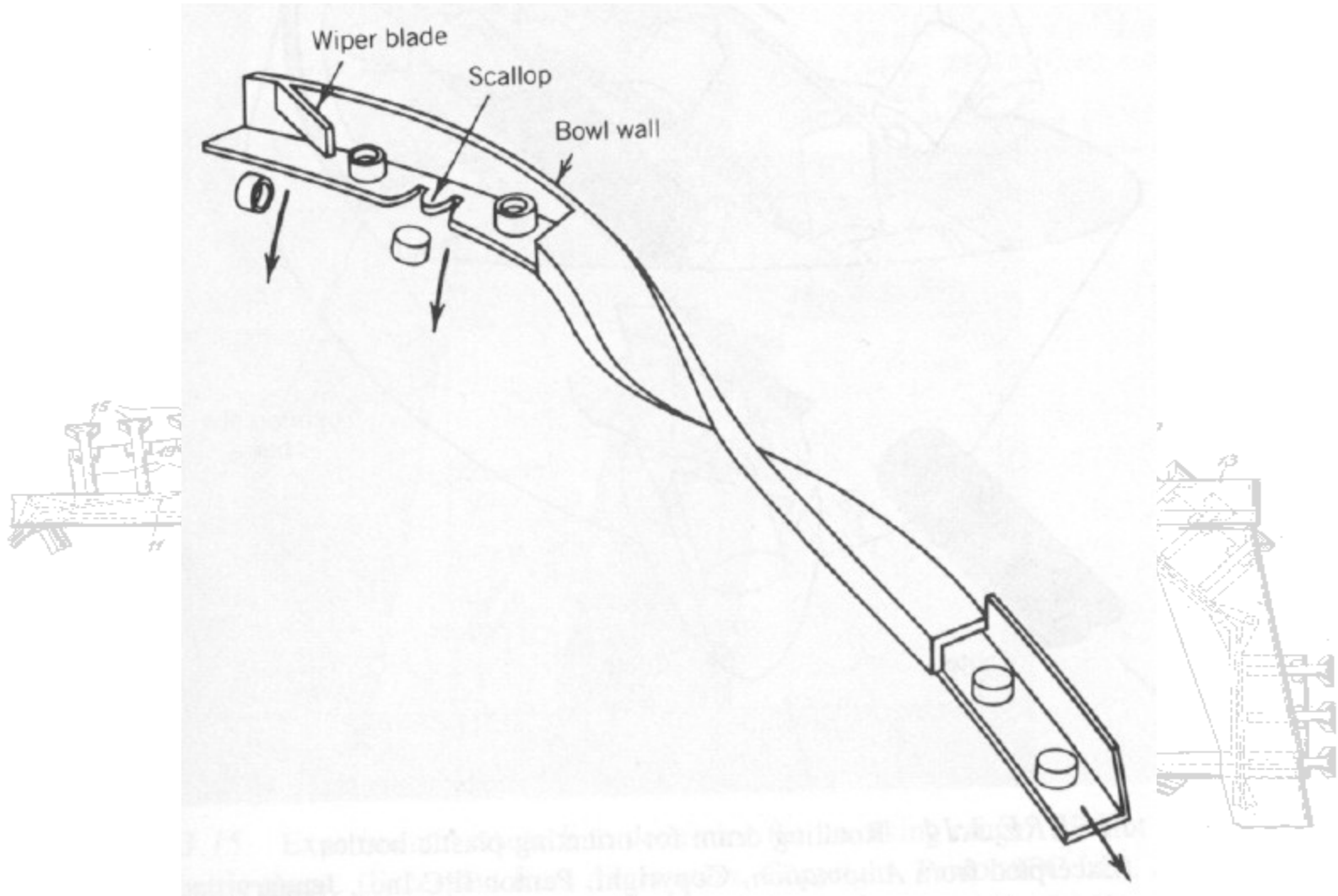
BOWL FEEDERS



BOWL FEEDERS



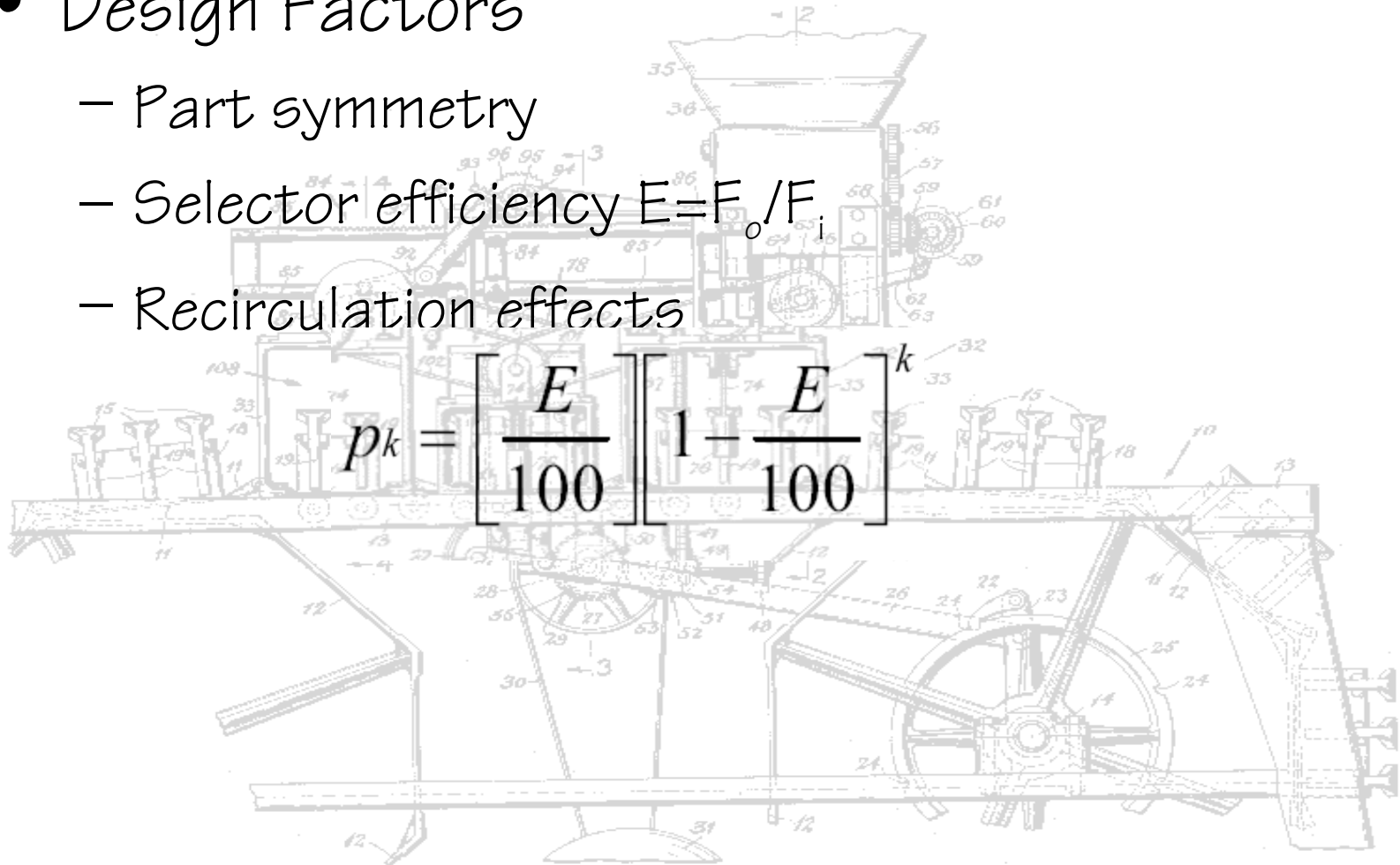
BOWL FEEDERS



BOWL FEEDERS

- Design Factors
 - Part symmetry
 - Selector efficiency $E = F_o / F_i$
 - Recirculation effects

$$p_k = \left[\frac{E}{100} \right] \left[1 - \frac{E}{100} \right]^k$$



BOWL FEEDERS - TRAP DESIGN

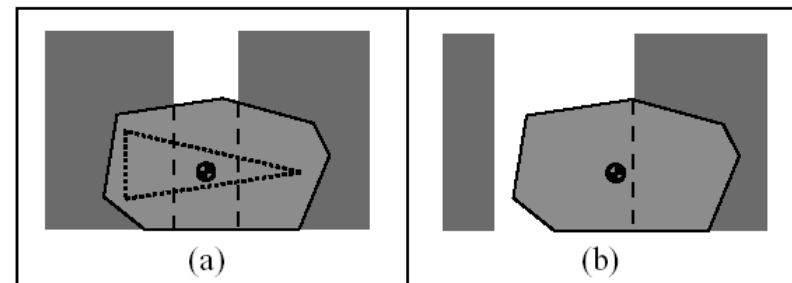
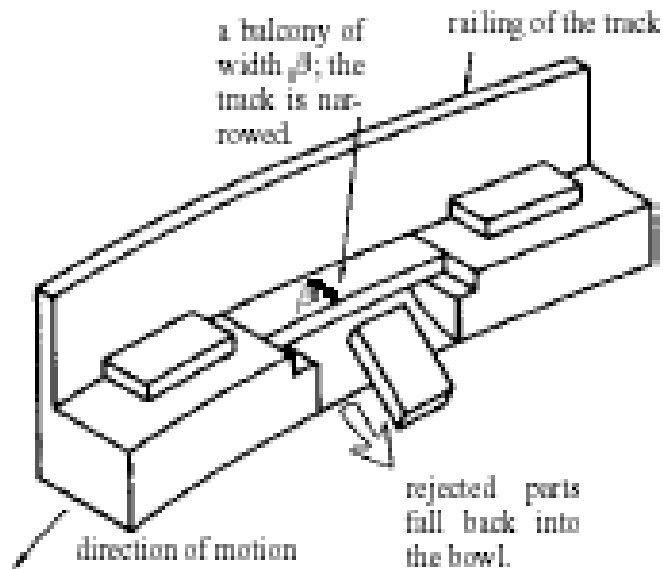


Figure 2: (a) A safe pose. The triangle is evidence of safe-ness. (b) An unsafe pose of the same part above a different trap.

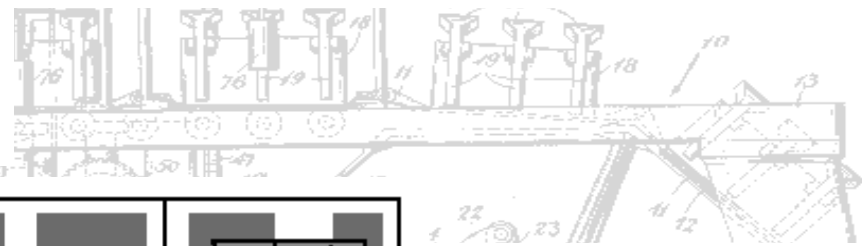
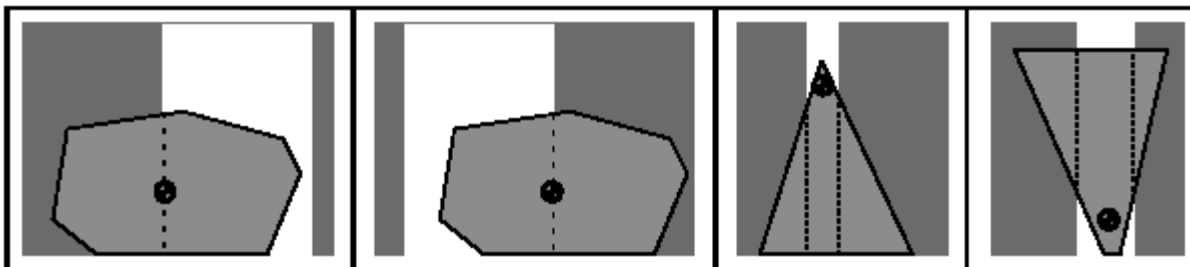
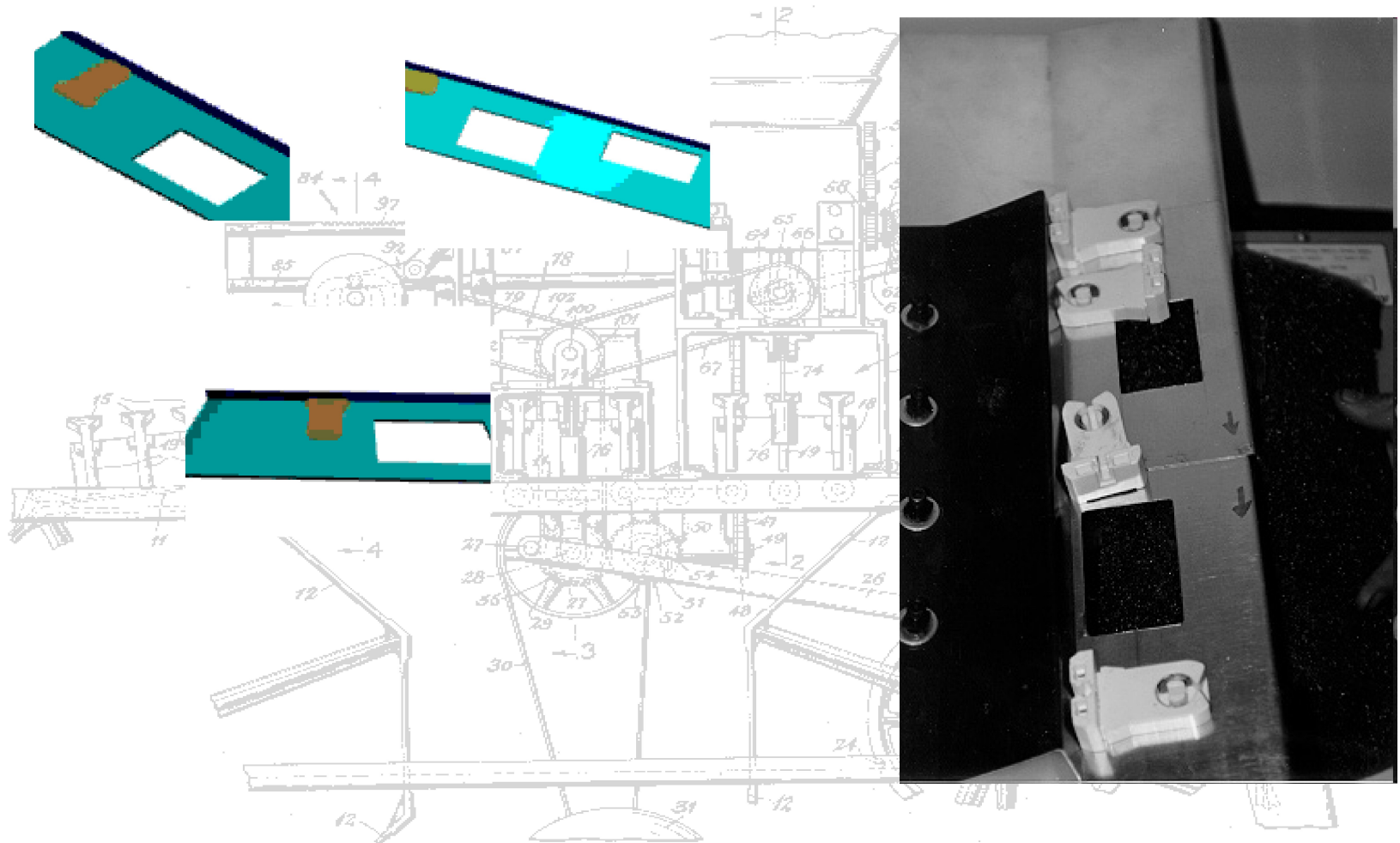


Figure 5: A critical pose.

Figure 4: The types of rejected poses.



BOWL FEEDERS - TRAP DESIGN



NON-VIBRATING FEEDERS

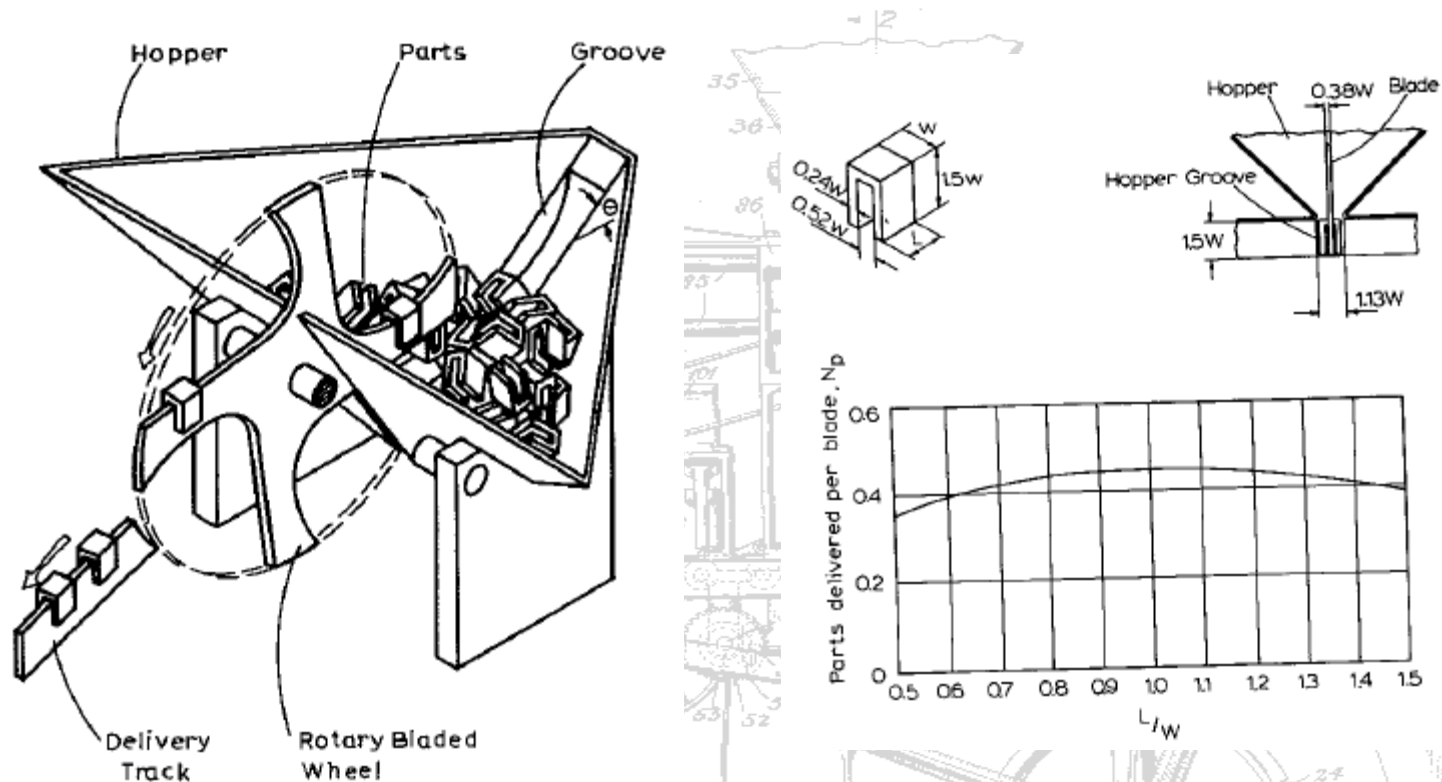


Fig. 4.34 Rotary centerboard hopper.

NON-VIBRATING FEEDERS

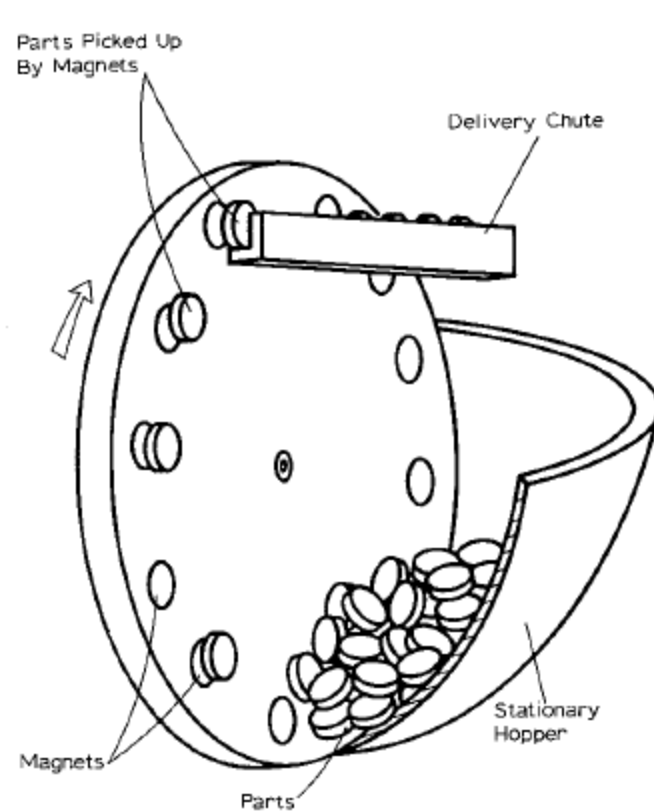
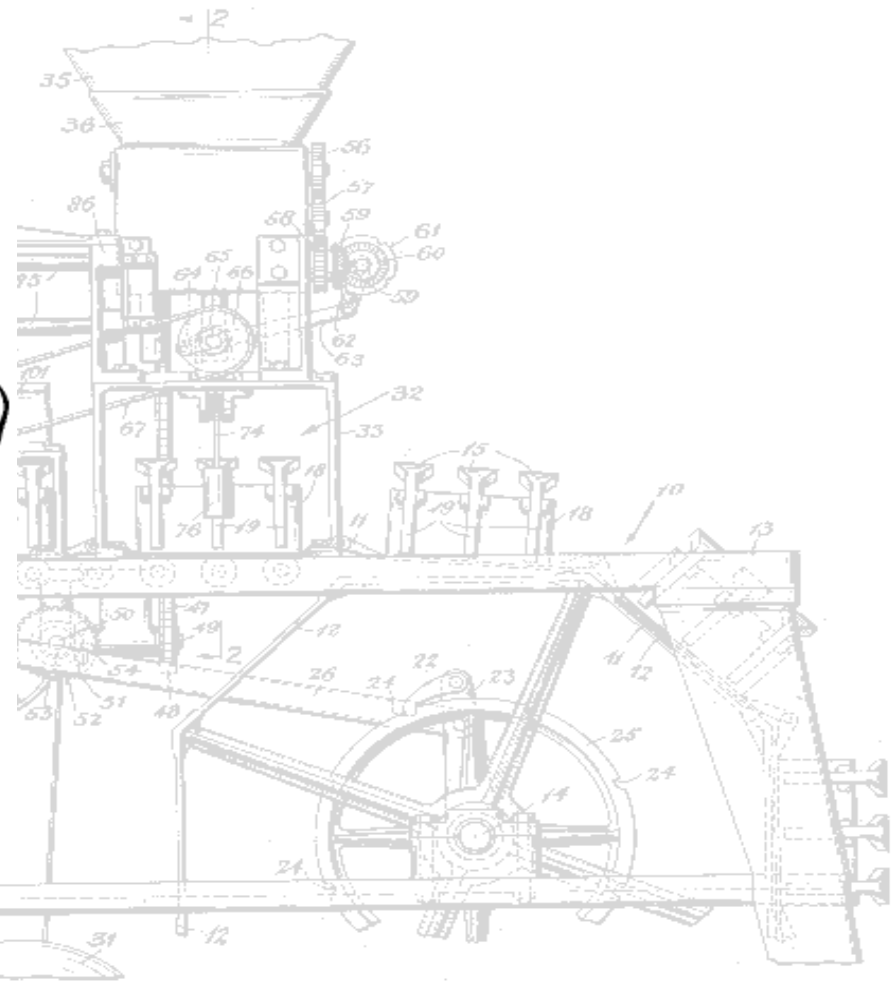
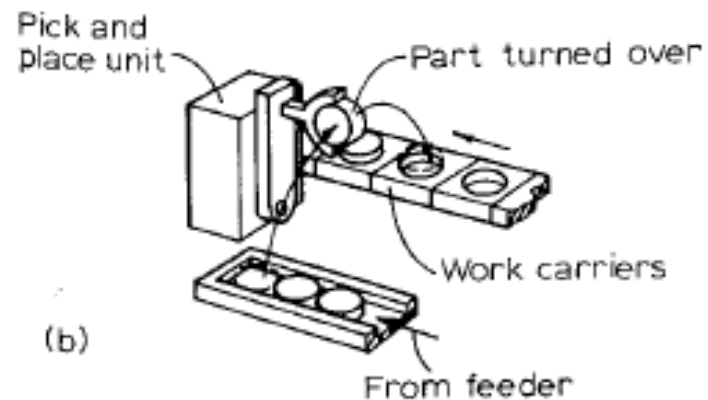
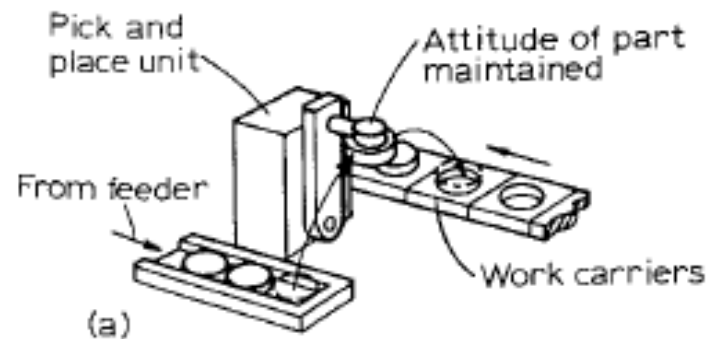
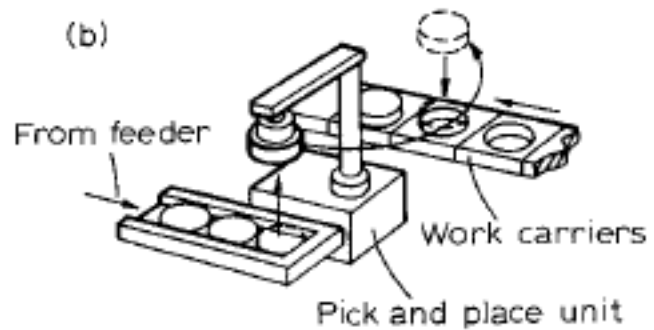
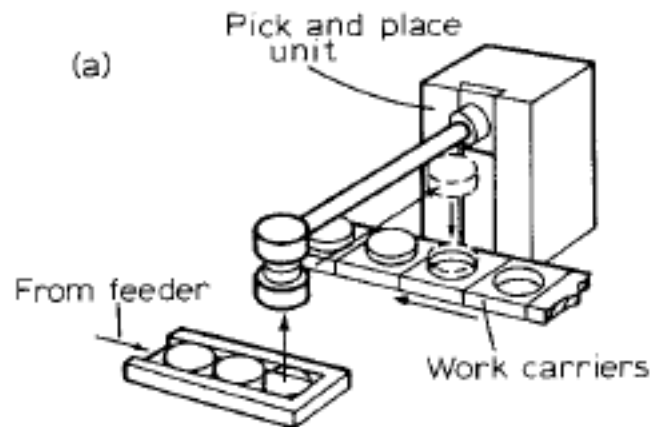


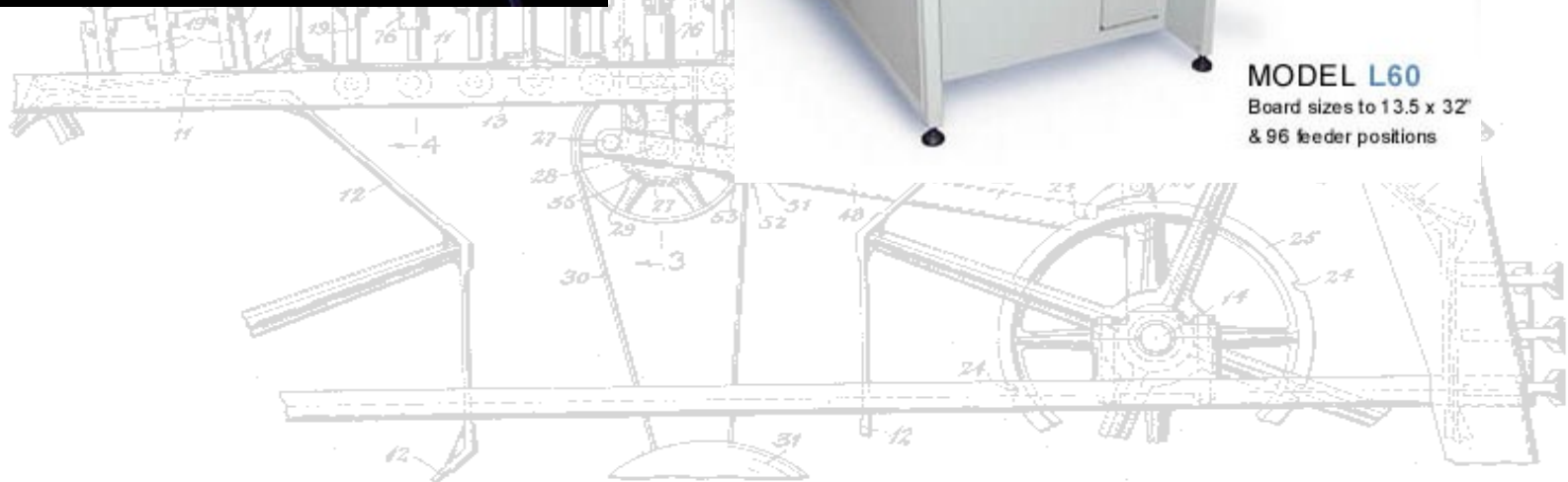
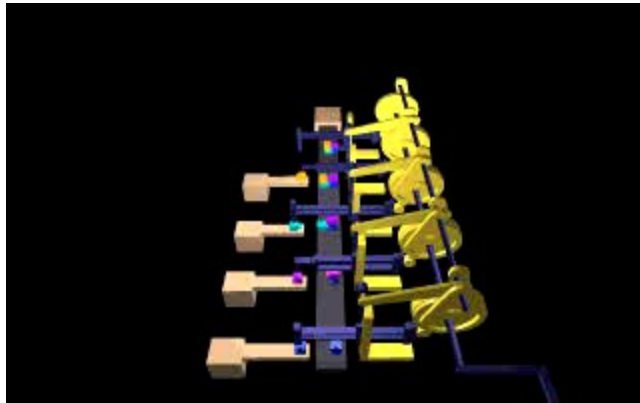
Fig. 4.36 Magnetic-disk feeder.



PICK & PLACE



PICK & PLACE



PRE-COLLATED COMPONENTS

