Anal yzing the Product

• Stapler example:





Anal yzing the Stapler

- What would cause the stapler not to work?
- What is the "architecture" of the stapler? (how parts are laid out, functions, arrangement in space)
- Liaison Diagram (p.4)





Liaison Diagram

- rivet connects anvil to base
- pin connects anvil, carrier, and handle
- carrier connects pusher and staples





Stapler Example

 What are some "Key Characteristics" that could affect function?

-In X direction:

- position of hammer
- thickness of hammer
- •anvil length
- position of pin & holes



Stapler Example

• Liaison Diagram with Key Characteristics



Manufacturing and Assembly Variation

- Engineering design of an assembly
 - Nominal design
 - Variation design
 - Process design

Nominal Design

- Determine ideal locations and orientations of parts
- Define mutual positioning constraints

Variation Design

- Determine allowable variation in location and orientation
- How much variation in each constraint can be tolerated and still achieve the key characteristics?

Process Design

- Determine fabrication and assembly processes that will contribute no more than the tolerable variation
- May require loosening allowable variation if no economical process exists

Variation Risk Management (VRM)

- Nominal Design, Variation Design, Process Design together make Variation Risk Management
- Very hard for many products

Example - Car Doors

- Door gap KC
- Weatherstripping KC



Car Door Example



Car Door Example

Making a door



Car Doors - Mounting



Car Doors - Mounting



GM Method of Mounting Doors to Car Bodies



Ford Method of Mounting Doors to Car Bodies

Mathematical Modeling of Assembly

- Coordinate frames
 - each part has a base coordinate frame
- Relationships between parts are expressed as 4x4 matrix transforms



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Matrix Math

- 4x4 matrices relate adjacent frames
- Matrix contains rotational part and translational part
- Translation occurs first, so rotation does not change position of new frame

Basic Translation and Rotation



$$T = \begin{bmatrix} r_{11} r_{12} r_{13} & p_x \\ r_{21} r_{22} r_{23} & p_y \\ r_{31} r_{32} r_{33} & p_z \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$T = \begin{bmatrix} R & p \\ 0^T & 1 \end{bmatrix}$$

Watch Transform Ordering!

$$T = \begin{bmatrix} R & p \\ 0^{T} & 1 \end{bmatrix}$$
$$= \begin{bmatrix} I & p \\ 0^{T} & 1 \end{bmatrix} * \begin{bmatrix} R & 0 \\ 0^{T} & 1 \end{bmatrix} * \begin{bmatrix} 0^{T} & 1 \end{bmatrix}$$
$$\neq \begin{bmatrix} R & 0 \\ 0^{T} & 1 \end{bmatrix} * \begin{bmatrix} I & p \\ 0^{T} & 1 \end{bmatrix} * \begin{bmatrix} I & p \\ 0^{T} & 1 \end{bmatrix} !!!$$

Composite Transforms

$$T_{02} = T_{01} T_{12}$$

$$T_{02} = \begin{bmatrix} R_{01} & p_{01} \\ 0^T & 1 \end{bmatrix} \begin{bmatrix} R_{12} & p_{12} \\ 0^T & 1 \end{bmatrix} = \begin{bmatrix} T_{02} & p_{12} \\ T_{02} & T_{12} \\ T_{02} & T_{12} \\ T_{02} & T_{12} \\ T_{02} & T_{12} \\ T_{12} & T_{12} \\ T_$$

Nominal Mating of Parts



The nominal location of part B can be calculated from the nominal location of part A using 4x4 transform math

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