

Driving Stepper Motors with DL06-CTRIO

Manual is at <http://www.automationdirect.com/static/manuals/hxctriom/hxctriom.pdf>

Template logic is at:

<http://wallawalla.edu/engr480> -> Programming Examples -> PIC -> working_stepper.zip

Steps to using the CTRIO or CTRIO2 module to control step motors:

1. Wire the CTRIO or CTRIO2 module to the STP-MTR-4035 motor amplifier
 - a) Y0 to STEP-
 - b) Y1 to DIR-
 - c) YC to ground
 - d) STEP+ to 2200ohm resistor which connects to +24V
 - e) DIR+ to another 2200ohm resistor which connects to +24V
2. Run CTRIO Workbench - Directsoft PLC (from Windows Start menu or DSLaunch6)
 - a) Do "Config I/O", set to Pulse Step/Direction
 - b) Do "I/O Map"
 - 1) Check "Enable Write to PLC"
 - 2) Use V2000 as address for inputs
 - 3) Check "Enable Read from PLC"
 - 4) Use V2030 as address for outputs
 - c) Create "Pulse Profiles"
 - 1) Add a profile
 - usually trapezoidal or S-curve for position, or dynamic velocity
 - set up appropriate values for acceleration, velocity, and number of pulses.
 - name your profile
 - 2) Add additional profiles as needed
 - d) Click "Write Module" (if "Write Module" is grayed out, click "Goto PROGRAM")
 - e) Click "Goto RUN"
3. Setup your PLC logic (project "working_stepper" is a good template to use)
 - a) Write "Load table" command (K10) to V2040.
 - b) Load profile table number into V2041.
 - c) Wait for command done bit to go true (B2022.7).
 - d) Set direction bit (B2056.4) to 0 or 1 as appropriate.
 - e) Set output enable bit (B2056.0) to 1. Your motor should turn.
 - f) Wait until output active bit (B2022.4) goes inactive (motion complete).
 - f) If you are going to do another motion profile immediately, delay briefly (10ms works).



