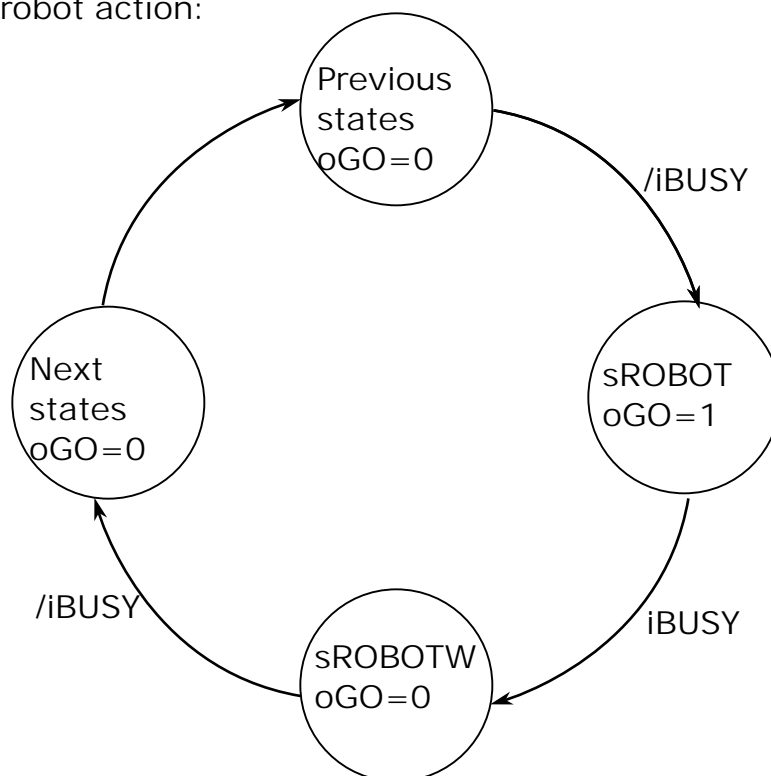


PLC logic to start a robot action:



Motoman INFORM code:

*LABEL

DOUT OT#(1) OFF

(output #1 is BUSY)

WAIT IN#(1)=ON

(input #1 is GO)

DOUT OT#(1) ON

MOVL ...

(do whatever moves you want here)

DOUT OT#(1) OFF

(turn off BUSY when move is done)

WAIT IN#(1)=OFF

(be sure PLC has acknowledged by turning of GO)

JUMP *LABEL