5I25
ANYTHING I/O
MANUAL

Version 1.7

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GENERAL

DESCRIPTION

The MESA 5I25 SuperPort is a low cost, general purpose programmable I/O card for the PCI bus. The 5I25 is a low profile PCI card and is available with standard or low profile brackets. The 5I25 uses standard parallel port pinouts and connectors for compatibility with most parallel port interfaced motion control / CNC breakout cards, allowing a motion control performance boost while retaining a reliable real time PCI interface.

The 5I25 is a universal PCI card so will work in 5V and 3.3V systems. The 5I25 provides 34 I/O bits (17 per connector). All I/O bits have bus switches that provide 5V tolerance and also have the benefit of disconnecting all I/O pins when the host CPU is off, preventing damage to the 5I25 if power is supplied to I/O pins when the host is powered down. All I/O pins have pull-up resistors, so have a defined state at power up. Unlike the parallel port that the 5I25 replaces, each I/O bit has individually programmable direction and function.

A power source option allows the 5I25 to supply 5V power to breakout boards if desired. This 5V power is protected by a per connector PTC.

Configurations are provided for hardware step generation (to MHz rates), encoder counting, PWM, digital I/O, analog I/O, and Smart Serial remote I/O.Configurations are available that are compatible with common breakout cards and multi axis step drives like the Probotix-RF and the Gecko G540.

There are currently five 5I25 compatible breakout cards available from Mesa, the 7I74 through 7I78.

The 7I74 is a eight channel RS-422 interface normally used with Mesa's Smart Serial remote I/O expansion cards. The 7I75 is a simple breakout/protection card that gives direct bidirectional access to all FPGA pins. The 7I76 is a step/dir oriented breakout with 5 axis of buffered step/dir outputs, one spindle encoder input, one isolated 0-10V analog spindle speed plus isolated direction and enable outputs, one RS-422 expansion port, 32 isolated 5-32V inputs and 16 isolated 5-32V 300 mA outputs. The 7I77 is a analog servo interface with 6 encoder inputs, 6 analog +-10V outputs, one RS-422 expansion port, 32 isolated 5-32V inputs, and 16 isolated 5-32V 300 mA outputs. The 5I25 supports two breakout cards so for example a 10 Axis step/dir configuration or 12 axis analog servo configuration is possible with a single 5I25 and two Mesa breakout cards. The 7I78 is a simple 4 axis buffered step/dir interface with isolated analog spindle control and spindle encoder interface plus one RS-422 port for I/O expansion.

HARDWARE CONFIGURATION

GENERAL

Hardware setup jumper positions assume that the 5I25 card is oriented in an upright position, that is, with the PCI connector towards the person doing the configuration.

BREAKOUT POWER OPTION

The 5I25 has the option to supply 5V power from the host computer to the breakout board. This option is used by all Mesa breakout boards to simplify wiring. The option uses 4 parallel cable signals that are normally used as grounds for supplying 5V to the remote breakout board (DB25 pins 22,23,24 and 25). These pins are AC bypassed on both the 5I25 and Mesa breakout cards so do not compromise AC signal integrity.

The 5V power option is individually selectable for the two I/O connectors. The breakout 5V power is protected by per connector PTC devices so will not cause damage to the 5I25 or system if accidentally shorted. This option should only be enabled for Mesa breakout boards or boards specifically wired to accept 5V power on DB25 pins 22 through 25. When the option is disabled DB25 pins 22 through 25 are grounded

W1 (P2 POWER)	W2 (P3 POWER)	
UP	UP	BREAKOUT POWER ENABLED
DOWN,	DOWN	BREAKOUT POWER DISABLED (*DEFAULT*)

5V I/O TOLERANCE

The FPGA used on the 5I25 has a 4V absolute maximum input voltage specification. To allow interfacing with 5V inputs, the 5I25 has bus switches on all I/O pins. The bus switches work by turning off when the input voltage exceeds a preset threshold. *The 5V I/O tolerance option is the default and should normally be left enabled.*

For high speed applications where only 3.3V maximum signals are present and overshoot clamping is desired, the 5V I/O tolerance option can be disabled. W3 controls the 5V I/O tolerance option. When W3 is on the default UP position, 5V tolerance mode is enabled. When W3 is in the DOWN position, 5V tolerance mode is disabled. Note that W3 controls 5V tolerance on both P2 and P3 I/O connectors.

W3 also selects the pull-up resistor voltage, When 5V I/O tolerance mode is selected, the I/O pull-up resistors are powered from 5V. When 5V I/O tolerance mode is disabled, the I/O pull-up resistors are powered with 3.3V.

HARDWARE CONFIGURATION

PRECONFIG PULLUP ENABLE

The Xilinx FPGA on the 5I25 has the option of having weak pull-ups on all I/O pins at power-up or reset. The default is to disable the pull-ups To enable the built-in pull-ups, (the default condition) jumper W4 should be placed in the UP position. To disable the internal pull-ups, W4 should be in the DOWN position.

PCI BUS ISOLATION

The 5I25 uses bus switches to provide 5V tolerance on the PCI bus. These bus switches can be turned off to disconnect the FPGA from the PCI bus. This is valuable when debugging FPGA PCI firmware. W5 controls the PCI bus isolate function. For normal operation W5 must be in the UP position. To disconnect the FPGA from the BUS, move W5 to the DOWN position.

CONNECTORS

CONNECTOR LOCATIONS AND DEFAULT JUMPER POSITIONS
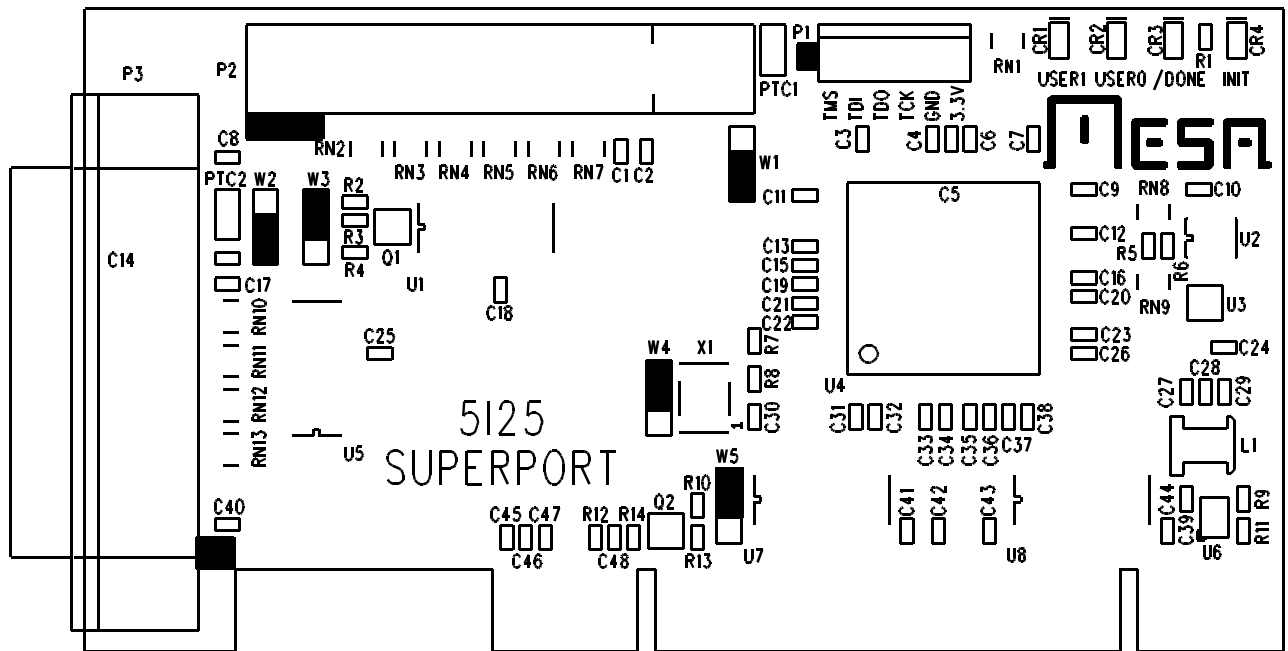
CONNECTORS

I/O CONNECTORS

The 5I25 has 2 I/O connectors, the primary DB25F connector P3 and the secondary 26 pin header connector P2, please see the 5I25IO.PIN file on the 5I25 distribution disk. 5I25 IO connector pinouts are as follows:

P3 BACK PANEL DB25F CONNECTOR PINOUT

DB25 PIN	FUNCTION	DB25 PIN	FUNCTION
1	IO0	14	IO1
2	IO2	15	IO3
3	IO4	16	IO5
4	IO6	17	IO7
5	IO8	18	GND
6	IO9	19	GND
7	IO10	20	GND
8	IO11	21	GND
9	IO12	22	GND or 5V
10	IO13	23	GND or 5V
11	IO14	24	GND or 5V
12	IO15	25	GND or 5V
13	IO16		

CONNECTORS

I/O CONNECTORS

P2 INTERNAL HDR26 CONNECTOR PINOUT

HDR PIN	FUNCTION	HDR PIN	FUNCTION
1	IO17	2	IO18
3	IO19	4	IO20
5	IO21	6	IO22
7	IO23	8	IO24
9	IO25	10	GND
11	IO26	12	GND
13	IO27	14	GND
15	IO28	16	GND
17	IO29	18	GND or 5V
19	IO30	20	GND or 5V
21	IO31	22	GND or 5V
23	IO32	24	GND or 5V
25	IO33	26	GND or 5V

Note: 26 pin header P2 will match standard parallel port pin-out if terminated with flat cable 26 pin receptacle/DB25F cable with pin1s connected (and header pin 26 left open)

A cable/bracket hardware kit is available from MESA for the second port.

CONNECTORS

JTAG CONNECTOR PINOUT

P1 is a JTAG programming connector. This is normally used only for debugging or if the EEPROM configuration has been corrupted. In case of corrupted EEPROM contents the EEPROM can be re-programmed using Xilinx's Impact tool. For reprogramming, the card can be powered in a standard PCI slot or if desired, 3.3V power can be applied via the JTAG connector.

P1 JTAG CONNECTOR PINOUT

PIN	FUNCTION
1	TMS
2	TDI
3	TDO
4	TCK
5	GND
6	+3.3V

OPERATION

FPGA

The 5I25 use a Xilinx Spartan6 ~400k gate FPGA in a 144 pin QFP package: XC6SLX9-PQ144.

FPGA PINOUT

The local bus and I/O interface FPGA pinouts are described in the 6i25.ucf file in the /configs/hostmot2/source directory of the 5i25.zip file.

PCI ACCESS

The 5I25 normally uses 5I25 specific HostMot2 firmware which currently has a simple target only PCI core with a single Base Address Register (BAR 0). Card specific PCI identifiers are as follows:

VENDOR ID   0X2718

DEVICE ID   0x5125

SUBSYSTEM VENDOR ID   0x2718

SUBSYSTEM DEVICE ID   0x5125

The single base address register (BAR0) maps a 64K Byte region of non-cacheble 32 bit wide memory.

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OPERATION

CONFIGURATION

The 5I25 is configured at power up by a SPI EEPROM. This EEPROM is an 8M bit chip that has space for two configuration files. Since all PCI bus logic on the 5I25 is in the FPGA, a problem with configuration means that PCI access will not be possible. This condition is only fixable by reprogramming the EEPROM via the JTAG connector P1, which is awkward and slow at best. For this reason the 5I25 EEPROM normally contains two configuration file images, A primary user image and a fallback image. If the primary user configuration is corrupted, the FPGA will load the fallback configuration so the EEPROM image can be repaired without having to resort to JTAG programming.

EEPROM LAYOUT

The EEPROM used on the 5I25 for configuration storage is the M25P80. The M25P80 is a 8 M bit (1 M byte) EEPROM with 16 64KByte sectors. Configuration files are stored on sector boundaries to allow individual configuration file erasing and updating. Standard EEPROM sector layout is as follows:

0x00000	BOOT BLOCK
0x10000	FALLBACK CONFIGURATION BLOCK 0
0x20000	FALLBACK CONFIGURATION BLOCK 1
0x30000	FALLBACK CONFIGURATION BLOCK 2
0x40000	FALLBACK CONFIGURATION BLOCK 3
0x50000	FALLBACK CONFIGURATION BLOCK 4
0x60000	FALLBACK CONFIGURATION BLOCK 5
0x70000	RESERVED
0x80000	USER CONFIGURATION BLOCK 0
0x90000	USER CONFIGURATION BLOCK 1
0xA0000	USER CONFIGURATION BLOCK 2
0xB0000	USER CONFIGURATION BLOCK 3
0xC0000	USER CONFIGURATION BLOCK 4
0xD0000	USER CONFIGURATION BLOCK 5
0xE0000	UNUSED/FREE
0xF0000	UNUSED/FREE

OPERATION

BITFILE FORMAT

The configuration utilities expects standard FPGA bitfiles without any multiboot features enabled. If multiboot FPGA files are loaded they will likely cause a configuration failure. In addition for fallback to work, the -g next_config_register_write:disable, -g reset_on_error:enable and -g CRC:enable bitgen options must be set.

MFLASH

The DOS utility program MFLASH is provided to write configuration files to the 5I25 EEPROM under DOS. MFLASH depends on a simple SPI interface built into both the standard user FPGA bitfiles and the fallback bitfile.

```
MFLASH FPGAFILE.BIT
```

Writes a standard bitfile FPGAFILE.BIT to the user area of the EEPROM

```
MFLASH FPGAFILE.BIT V
```

Verifies the user EEPROM configuration against the bit file FPGAFILE.BIT

```
MFLASH FALLBACK.BIT FallBack
```

Writes the fallback EEPROM configuration to the fallback area of the EEPROM. In addition if the bootblock is not present in block 0 of the EEPROM, it re-writes the bootblock.

MESAFLASH

Linux and Windows utility programs mesaflash and mesaflash.exe are provided to write configuration files to the 5I25 EEPROM. These files depend on a simple SPI interface built into both the standard user FPGA bitfiles and the fallback bitfile.

If mesaflash is run with no command line arguments it will print usage information.

```
mesaflash --device 5I25 --write FPGAFILE.BIT
```

Writes a standard bitfile FPGAFILE.BIT to the user area of the EEPROM

```
mesaflash --device 5I25 --verify FPGAFILE.BIT
```

Verifies the user EEPROM configuration against the bit file FPGAFILE.BIT

```
mesaflash --device 5I25 --write FALLBACK.BIT --fallback
```

OPERATION

SPI INTERFACE DESCRIPTION

This is the register level description of the simple SPI interface to the 5I25's configuration EEPROM. This hardware is built into all Mesa 5I25 configurations. This information is only needed if you are writing your own programming utility.

DATA REGISTER at offset 0x74 from 5I25 base address

D7	D6	D5	D4	D3	D2	D1	D0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

CONTROL REGISTER at offset 0x70 from 5I25 base address

X	X	X	X	X	DAV	BUSY	CS
X	X	X	X	X	R/O	R/O	R/W

OPERATION

SPI INTERFACE DESCRIPTION

The SPI interface is very minimal, just enough hardware to avoid slow bit banging of the SPI data when reading or writing the configuration EEPROM. Operation is as follows: To transfer SPI data, CS is asserted low and an outgoing command/data byte is written to the data register. This write to the data register causes the SPI interface to clear its DAV bit, shift out its outgoing data byte, and shift in its incoming data. This shifting is done at a fixed PCI Clock/3 rate or about 11 MHz. When the byte data transfer is done, The DAV bit is set in the control register. Host software can poll this bit to determine when the transfer is done. When the transfer is done the incoming data from the EEPROM can be read in the data register, and the next byte sent out.

Note that CS operation is entirely controlled by the host, that is for example with a 5 byte command sequence, the host must assert CS low, transfer 5 bytes with 5 write/read commands to the data register with per byte DAV bit polling and finally assert CS high when done.

FREE EEPROM SPACE

Three 64K byte blocks of EEPROM space are free when both user and fallback configurations are installed. It is suggested that only the last two blocks, 0xE0000 and 0xF0000 in the user area, be used for FPGA application EEPROM storage.

FALLBACK INDICATION

Mesa's supplied fallback configurations blink the red INIT LED on the top right hand side of the card if the primary configuration fails and the fallback configuration loaded successfully. If this happens it means the user configuration is corrupted or not a proper configuration for the 5I25s FPGA. This can be fixed by running the configuration utility and re-writing the user configuration.

FAILURE TO CONFIGURE

The 5I25 should configure its FPGA within a fraction of a second of power application. If the FPGA card fails to configure, both red LEDs on the right hand side of the card will remain illuminated after power up. If this happens the 5I25s EEPROM must be re-programmed via the JTAG connector.

CLOCK SIGNALS

The 5I25 has two FPGA clock signals. One is the PCI clock and the other is a 50 MHz crystal oscillator on the 5I25 card. Both clocks a can be multiplied and divided by the FPGAs clock generator block to generate a wide range of internal clock signals. Note that the PCI bus clock is often not known to a high degree of accuracy so for accurate timing applications, the on card 50 MHz oscillator should be used.

OPERATION

LEDS

The 5I25 has 2 FPGA driven user LEDs (User 0 and User 1 = Green), and 2 status LEDs (red). The user LEDs can be used for any purpose, and can be helpful as a simple debugging feature. A low output signal from the FPGA lights the LED. See the 5I25IO.PIN file for FPGA pin locations of the LED signals. The status LEDs reflect the state of the FPGA's DONE, and /INIT pins. The /DONE LED lights until the FPGA is configured at power-up. The /INIT LED lights when the power on reset is asserted, when there has been a CRC error during configuration. When using Mesas configurations, the /INIT LED blinks when the fallback configuration has been loaded.

PULLUP RESISTORS

All I/O pins are provided with pull-up resistors to allow connection to open drain, open collector, or OPTO devices. These resistors have a value of 3.3K so have a maximum pull-up current of 1.5 mA (5V pull-up) or 1 mA (3.3V pull-up).

IO LEVELS

The Xilinx FPGAs used on the 5I25 have programmable I/O levels for interfacing with different logic families. The 5I25 does not support use of the I/O standards that require input reference voltages. All standard Mesa configurations use LVTTL levels.

Note that even though the 5I25 can tolerate 5V signal inputs, its outputs will not swing to 5V. The outputs are push pull CMOS that will drive to the output supply rail of 3.3V. This is sufficient for TTL compatibility but may cause problems with some types of loads. For example when driving an LED that has its anode connected to 5V, in such devices as OPTO isolators and I/O module rack SSRs, the 3.3V high level may not completely turn the LED off. To avoid this problem, either drive loads that are ground referred, Use 3.3V as the VCC for VCC referred loads, or use open drain mode.

STARTUP I/O VOLTAGE

After power-up or system reset and before the the FPGA is configured, the pull-up resistors will pull all I/O signals to a high level. If the FPGA is used for motion control or controlling devices that could present a hazard when enabled, external circuitry should be designed so that this initial state results in a safe condition.

OPERATION

INTERFACE CABLES

Mesa daughtercards use a male to male DB25 cable to interface to the 5I25. For noise immunity and signal fidelity it is suggested that only IEEE-1284 rated cables be used. IEEE-1284 rated cables have a twisted pair shield wire for each signal wire and an overall shield terminated in the metal connector shell. This results in much better performance than flat or NON-IEEE-1284 parallel port cables For short connections of less than 3 feet, flat cables can be used. No other type of cable should be used.

Mesa can supply IEEE-1284 cables tested with the 5I25 / daughtercard combination in 6 and 10 foot lengths.

BREAKOUT POWER OPTION

When used with Mesa breakout/daughter cards, the 5I25 can supply up to 1A of 5V power to each of the daughter cards. This option is disabled by default to avoid possible damage to standard breakout boards, so must be specifically enabled for Mesa daughtercards. If you use this option you must verify that the interface cable does not tie the eight parallel port ground wires together as some cheap printer cables do. Mesa supplied IEEE-1284 cables are the best option for Mesa daughter cards and are guaranteed to work with the power option. Flat cable will work as well but have poorer noise immunity and signal fidelity.

PLUG AND GO KITS

Motion control kits with pre-programmed 5I25, interface cable, and daughtercard(s) are available to simplify system integration.

SUPPLIED CONFIGURATIONS

HOSTMOT2

All supplied configurations are part of the HostMot2 motion control firmware set. All HostMot2 firmware is open source and easily extendible to support new interfaces or different sets of interfaces embedded in one configuration. For detailed register level information on Hostmot2 firmware modules, see the regmap file in the hostmot2 source code directory.

7I76X2

7I76X2 is a configuration intended to work with the 7I76 five axis step/dir daughtercard. It will support two 7I76 daughtercards, one on each of the 5I25s I/O connectors. The configuration includes ten hardware step generators, two encoder inputs and four Smart Serial interfaces, a watchdog timer and GPIO.

7I76_7I74

7I76_7I74 is a configuration for one 7I76 five axis step/dir daughtercards on P3 and one 7I74 eight channel RS-422 interface on P2. The 7I74 is configured with eight Smart Serial channels.

G540X2

G540X2 is a configuration intended to work with two Gecko G540 four axis step motor drives. It includes eight hardware step generators, two PWM generators, four GPIO outputs, eight GPIO inputs, two charge pump drivers and a watchdog timer.

7I77X2

7I77X2 is a configuration intended to work with the 7I77 six axis analog servo daughtercard. It will support two 7I77 daughtercards. It includes twelve encoder inputs, six smart serial interfaces (four used locally on the 7I77s and two fed through for additional remotes), a watchdog timer and GPIO.

7I77_7I76

7I77_7I76 is a configuration intended to work with a 7I77 six axis analog servo daughtercard on P3 and a 7I76 daughtercard on P2.

SUPPLIED CONFIGURATIONS

7I77_7I74

7I74_7I77 is a configuration intended to work with one 7I77 six axis analog servo daughtercard on P3 and one 7I74 eight channel RS-422 interface daughtercard on P2. It includes 12 encoder inputs, 11 smart serial interfaces (two used on the 7I77 for 48 bit isolated field I/O and analog out) , a watchdog timer and GPIO.

7I74X2

7I74X2 is a configuration intended to work with two 7I74 RS-422 daughter cards It include sixteen smart serial interfaces allowing real time control of up to 768 digital I/O points, a watchdog timer and GPIO.

7I78X2

7I78X2 is a configuration intended to work with the 7I78 four axis step/dir daughtercard. It will support two 7I78 daughtercards, one on each of the 5I25s I/O connectors. The configuration includes eight hardware step generators, two PWM generators, two encoder inputs, two Smart Serial interfaces, a watchdog timer and GPIO.

7I76_7I78

7I76_7I78 is a configuration designed to work with the 7I76 five axis step/dir daughtercard on P3 and a 7I78 4 axis step/dir daughtercard on P2. The configuration includes nine hardware step generators, two PWM generators, two encoder inputs, two Smart Serial interfaces, a watchdog timer and GPIO

PROB_RFX2

The PROB_RFX2 configuration is a step/dir configuration intended to work with most common parallel port breakouts. Two breakouts are supported, one on each of the 5I25s I/O connectors. The configuration includes eight hardware step generators, two encoders with index, two PWM generators , a watchdog timer and GPIO.

PIN FILES

Each of the configurations has an associated file with file name extension .pin that describes the FPGA functions included in the configuration and the I/O pinout. These are plain text files that can be printed or viewed with any text editor.

REFERENCE

SPECIFICATIONS

POWER	MIN	MAX	NOTES:
3.3V POWER SUPPLY	3.0V	3.6V	PCI supplied 3.3V
5V POWER SUPPLY	4.5V	5.5V	PCI supplied 5V
3.3V POWER CONSUMPTION:	----	400 mA	Depends on FPGA Configuration
MAX 5V CURRENT TO I/O CONNS	---	1000 mA	Each (PTC Limit)
TEMPERATURE RANGE -C version	0 ^{o}C	+70 ^{o}C	
TEMPERATURE RANGE -I version	-40 ^{o}C	+85 ^{o}C	